Chopper/Inverter Control Function Set 581453 (9069-20)



LabVolt Series

Datasheet

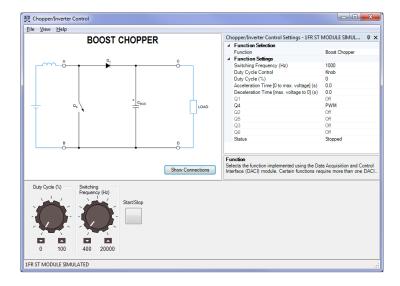


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General Description

The Chopper/Inverter Control Function Set enables the following choppers and inverters to be implemented using the Data Acquisition and Control Interface, the IGBT Chopper/Inverter and the Insulated DC-to-DC Converter:

- Buck Chopper (high-side switching)
- Buck Chopper (low-side switching)
- Buck/Boost Chopper
- Boost Chopper
- Four-Quadrant Chopper
- Buck Chopper with Feedback
- Boost Chopper with Feedback
- Single-Phase, 180° Modulation Inverter
- Single-Phase PWM Inverter
- Three-Phase, 180° Modulation Inverter
- Three-Phase PWM Inverter
- Three-Phase Inverter (constant V/f ratio)
- Insulated DC-to-DC Converter
- Four-Quadrant DC Motor Drive without Current Control
- Four-Quadrant DC Motor Drive

Specifications

Parameter	Value
Control Functions	
Control Functions	Buck Chopper (high-side switching)
	Buck Chopper (low-side switching)
	Buck/Boost Chopper
	Boost Chopper
	Four-Quadrant Chopper
	Buck Chopper with Feedback
	Boost Chopper with Feedback
	Single-Phase, 180° Modulation Inverter
	Single-Phase PWM Inverter
	Three-Phase, 180° Modulation Inverter
	Three-Phase PWM Inverter
	Three-Phase PWM Inverter (constant V/f ratio)
	Insulated DC-to-DC Converter
	Four-Quadrant DC Motor Drive without Current Control
	Four-Quadrant DC Motor Drive
Buck Chopper (high-side switching), Buck Chopper	
(low-side switching), Buck/Boost Chopper, Boost	
Chopper, Four-Quadrant Chopper	
Switching Frequency	400 Hz to 20 kHz
Duty Cycle Control	Knob or analog input on the DACI
Duty Cycle	0-100%
Acceleration Time (0 to Max. Voltage)	0-100 s
Deceleration Time (Max. Voltage to 0)	0-100 s
IGBTs Q1 to Q6	PWM, on, off (certain IGBTs are unavailable depending on the selected chopper control function)

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Parameter	Value
Buck Chopper with Feedback, Boost Chopper with	
Feedback Cuitabine Fermion	2.20 kHz
Switching Frequency	2-20 kHz
Command Input	Knob or analog input on the DACI
Command	0-100%
Feedback Input	Voltage, current, speed, power, or low-power analog signal
Feedback Filter Cutoff Frequency	100-4900 Hz
Feedback Range (100% Value =)	10-400 V
Acceleration Time (0 to 100%)	0-100 s
Deceleration Time (100% to 0)	0-100 s
Single-Phase, 180° Modulation Inverter	
DC Bus	Unipolar or bipolar
Frequency	0-120 Hz
IGBTs Q1 to Q6	180° Modulation, on, or off (certain IGBTs are unavailable)
Single-Phase PWM Inverter	
DC Bus	Unipolar or bipolar
Switching Frequency	400 Hz to 20 kHz
Frequency	0-120 Hz
Peak Voltage	0-100% of dc bus
IGBTs Q1 to Q6	PWM, on, or off (certain IGBTs are unavailable)
Three-Phase, 180° Modulation Inverter	
Phase Sequence	Forward (1-2-3), reverse (1-3-2), or forward/reverse
Frequency	0-120 Hz
IGBTs Q1 to Q6	180° Modulation, on, or off
Three-Phase PWM Inverter	· ·
Switching Frequency	400 Hz to 20 kHz
Phase Sequence	Forward (1-2-3), reverse (1-3-2), or forward/reverse
Frequency	0-120 Hz
Peak Voltage	0-117% of dc bus/2
Modulation Type	Sinusoidal pulse-width modulation or space vector
IGBTs Q1 to Q6	PWM, on, or off
Three-Phase PWM Inverter (Constant V/f Ratio)	1 1111, 311, 31 31
Switching Frequency	400 Hz to 20 kHz
Phase Sequence	Forward (1-2-3), reverse (1-3-2), or forward/reverse
	0-120°
Frequency Know Book Voltage	0-117% of dc bus voltage/2
Knee Peak Voltage	<u> </u>
Knee Frequency	1-120 Hz
Modulation Type	Sinusoidal pulse-width modulation or space vector
Acceleration Time (0 to Knee)	0-100 s
Deceleration Time (Knee to 0)	0-100 s
Insulated DC-to-DC Converter	0.4504
Duty Cycle	0-45%
Four-Quadrant DC Motor Drive with and without	
Current Control	2-20 kHz
Switching Frequency	
Speed Command Input	Knob or analog input on the DACI
Speed Command	-5000 r/min to 5000 r/min
Pulley Ratio	24:12 or 24:24
Acceleration Time (0 to Max. Speed)	0-100 s
Deceleration Time (Max. Speed to 0)	0-100 s
Current Feedback Range	4 A or 40 A (only available in current control)
Current Feedback Filter Cutoff Frequency	100-4900 Hz (only available in current control)
Current Command Limit	0-40 A (only available in current control)

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