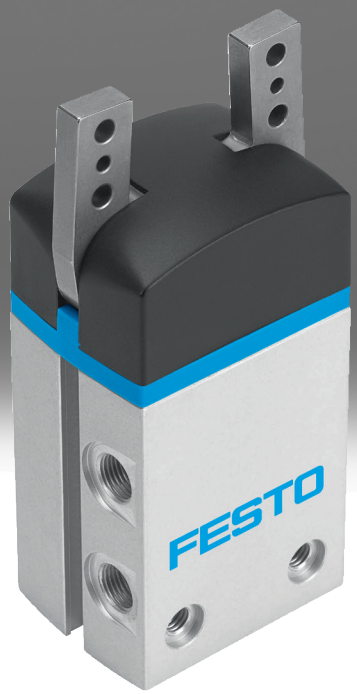
Angle gripper DHWS



Characteristics

At a glance Link dhws

General information:
- Improved gripper jaw guide
- Slotted guide
- Max. repetition accuracy
- Gripping force backup
- Internal fixed flow control
- Wide range of adaptation options on the drives

Sensors:
- Adaptable position sensor for small gripper sizes
- Integrated proximity switches for medium and large gripper sizes

Flexible range of applications:
- Can be used as a double-acting and single-acting gripper
- Compression spring for supporting or retaining the gripping forces
- Suitable for external and internal gripping

These grippers are not designed for the following or similar application examples:
- Machining
- Aggressive media
- Grinding dust
- Welding spatter

Engineering tools Link engineering tools

Save time with engineering tools: Smart engineering for the optimal solution. Our goal is to increase your productivity. Our engineering tools play an integral part in achieving this goal. They help you size your system correctly, tap into unimagined productivity reserves and generate additional productivity along the entire value chain. In every phase of your project, from the initial contact to the modernisation of your machine, you will come across a number of different tools that will be of use to you.

Gripper selection:
- This tool helps you to select the right grippers by simply entering the exact parameters for your application

Diagrams Link dhws

The diagrams shown in this document are also available online. These can be used to display precise values.

Position sensing

[A]	For proximity sensor

By using proximity switches, any position can be detected.

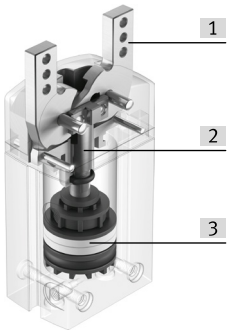
Gripping force backup

[NC]	Closing

Closed by spring force in depressurised state

Characteristics

Overview



[1] Gripper jaw
[2] Link
[3] Piston with magnet

Type code

001	Series	
DHWS	Angle gripper	

002	Size [mm]	
10	10	
16	16	
25	25	
32	32	
40	40	

003	Position sensing	
A	For proximity sensor	

004	Gripping force backup	
	None	
NC	Closing	

Datasheet

General technical data					
Size	10	16	25	32	40
Design	Lever				
Mode of operation	Double-acting				
Gripping force backup	None	None Closing			
Gripper function	Bracket				
Number of gripper jaws	2				
Max. opening angle	40 deg				
Pneumatic connection	M3		M5	G1/8	
Repetition accuracy, gripper [1]	≤0.04 mm				
Max. replacement accuracy	≤0.2 mm				
Max. operating frequency of gripper	≤4 Hz		≤3 Hz		
Rotationally symmetrical	≤0.2 mm				
Position detection	Via Hall sensor	Via proximity switch			
Type of mounting	Either: Via female thread and centring sleeve Via through-hole and centring sleeve				
Mounting position	Any				

1) Under constant exposure to operating conditions, end-position drift occurs in the direction of movement of the gripper jaws, at 100 consecutive strokes

Operating and environmental conditions					
Size	10	16	25	32	40
Operating medium	Compressed air to ISO 8573-1:2010 [7:4:4]				
Note on operating and pilot medium	Lubricated operation possible (in which case lubricated operation will always be required)				
Ambient temperature [1]	5 ... 60°C				
Corrosion resistance class CRC [2]	1 - Low corrosion stress				

1) Note the operating range of the proximity switches

2) More information: www.festo.com/x/topic/crc

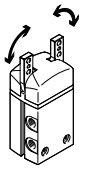
Operating pressure								
Size	10	16		25		32		40	
Gripping force backup	None	Closing	None	Closing	None	Closing	None	Closing	None	Closing
Operating pressure	2 ... 8 bar	4 ... 8 bar	2 ... 8 bar	4 ... 8 bar	2 ... 8 bar	4 ... 8 bar	2 ... 8 bar	4 ... 8 bar

Weight									
Size	10	16		25		32		40	
Gripping force backup	None	Closing	None	Closing	None	Closing	None	Closing	None	Closing
Product weight	40 g	110 g	114 g	258 g	265 g	452 g	462 g	775 g	790 g

Materials					
Size	10	16	25	32	40
Material housing	Wrought aluminium alloy, Hard anodised				
Material gripper jaws	High-alloy steel				
Material cover cap	PA				
Note on materials	RoHS compliant				
LABS (PWIS) conformity	VDMA24364-B2-L				
Suitability for the production of Li-ion batteries	Metals with more than 5% by mass of copper are excluded from use. Exceptions are printed circuit boards, cables, electrical connectors and coils.				

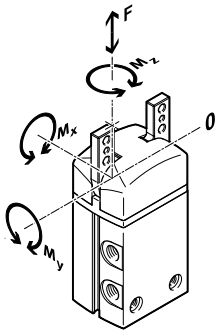
Datasheet

Gripping torque



Size	10	16	25	32	40
Total gripping torque at 0.6 MPa (6 bar, 87 psi), opening	43 Ncm	129 Ncm	386 Ncm	810 Ncm	1,497 Ncm
Total gripper torque, closing, 0.6 MPa (6 bar, 87 psi)	30 Ncm	114 Ncm	356 Ncm	746 Ncm	1,362 Ncm

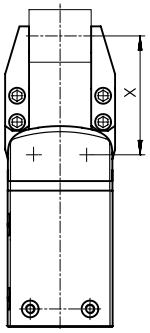
Characteristic load values at the gripper jaws



The indicated permissible forces and torques apply to a single gripper jaw. They include the lever arm, additional applied loads created by the workpiece or external gripper fingers and acceleration forces occurring during movement. The zero coordinate line (gripper jaw guide) must be taken into account when calculating torques.

Size	10	16	25	32	40
Max. force on gripper jaw Fz static	25 N	50 N	90 N	120 N	200 N
Max. torque at gripper Mx static	0.6 Nm	1.6 Nm	3.6 Nm	6 Nm	13 Nm
Max. torque at gripper My static	0.6 Nm	1.6 Nm	3.6 Nm	6 Nm	13 Nm
Max. torque at gripper Mz static	0.6 Nm	1.6 Nm	3.6 Nm	6 Nm	13 Nm

Gripping force FH per gripper jaw as a function of operating pressure and lever arm x

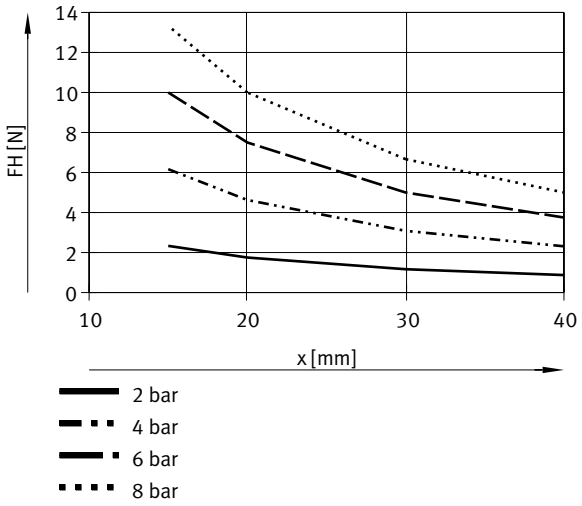


The gripping forces as a function of operating pressure and lever arm can be determined from the following graphs.
The gripping torque is not constant across the opening angle.

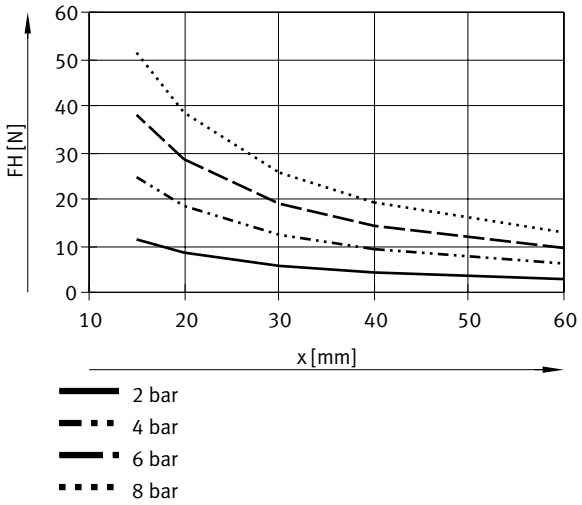
Sizing software for gripper selection → https://www.festo.com/x/topic/eng

Datasheet

Gripping force FH per gripper jaw as a function of operating pressure and lever arm x – external gripping (closing), double-acting – DHWS-10

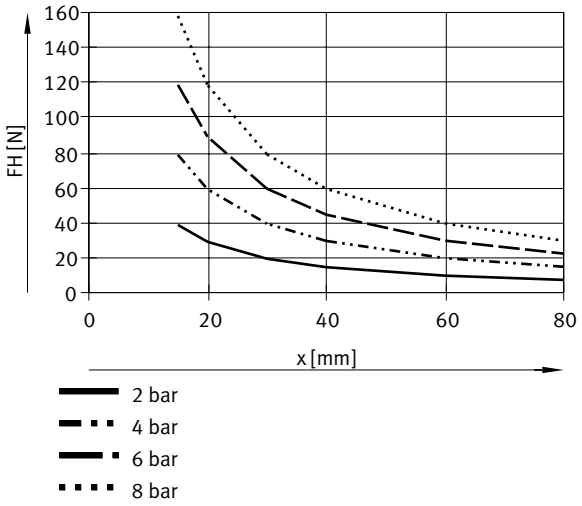


Gripping force FH per gripper jaw as a function of operating pressure and lever arm x – external gripping (closing), double-acting – DHWS-16

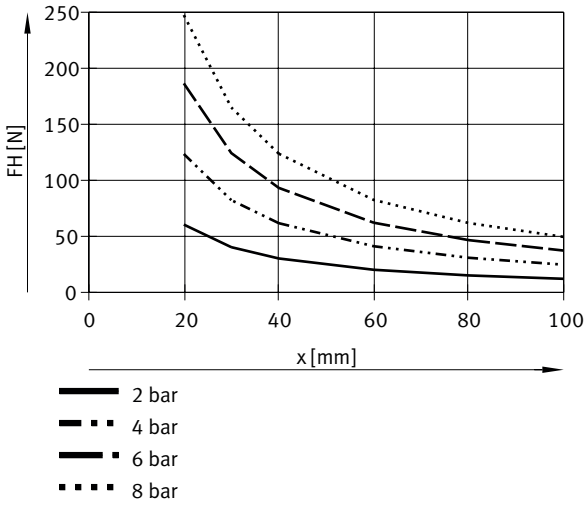


Datasheet

Gripping force FH per gripper jaw as a function of operating pressure and lever arm x – external gripping (closing), double-acting – DHWS-25

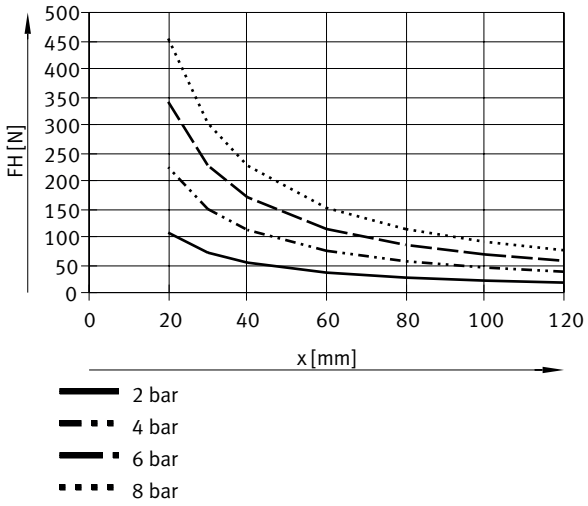


Gripping force FH per gripper jaw as a function of operating pressure and lever arm x – external gripping (closing), double-acting – DHWS-32

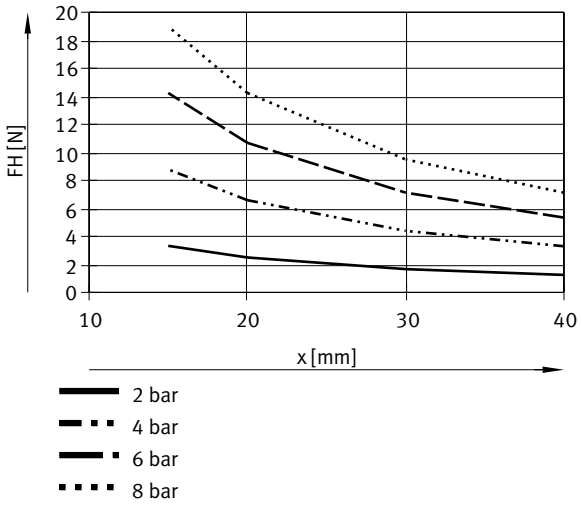


Datasheet

Gripping force FH per gripper jaw as a function of operating pressure and lever arm x – external gripping (closing), double-acting – DHWS-40

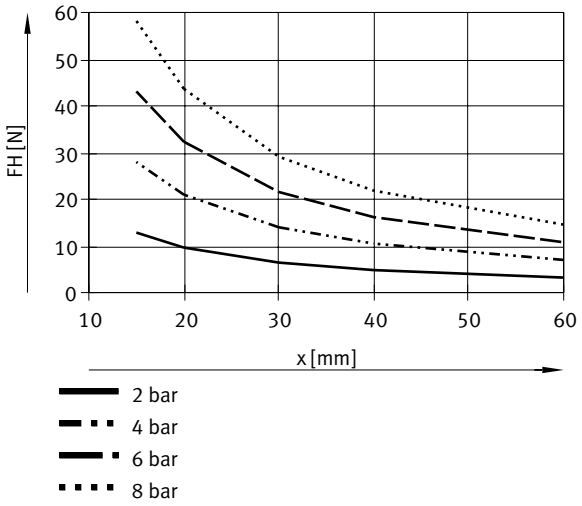


Gripping force FH per gripper jaw as a function of operating pressure and lever arm x – internal gripping (opening), double-acting – DHWS-10

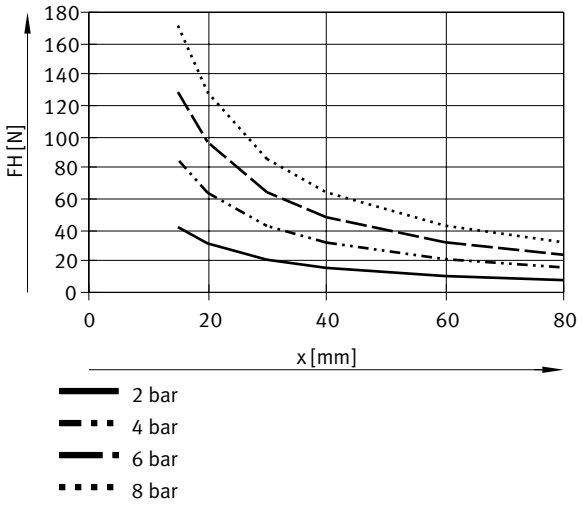


Datasheet

Gripping force FH per gripper jaw as a function of operating pressure and lever arm x – internal gripping (opening), double-acting – DHWS-16

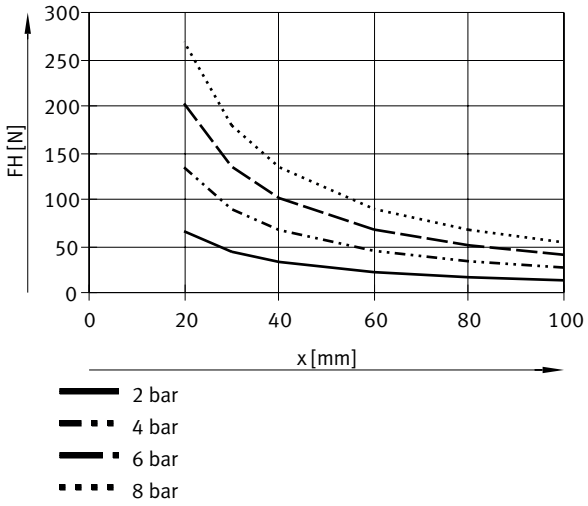


Gripping force FH per gripper jaw as a function of operating pressure and lever arm x – internal gripping (opening), double-acting – DHWS-25

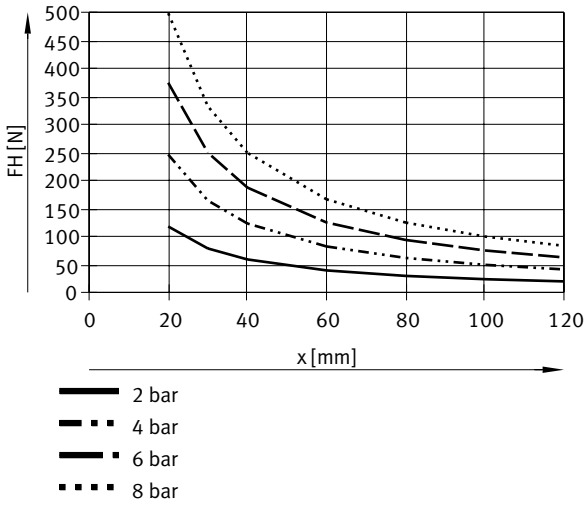


Datasheet

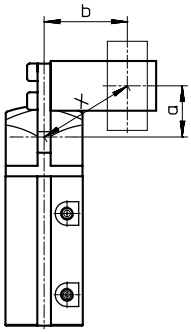
Gripping force FH per gripper jaw as a function of operating pressure and lever arm x – internal gripping (opening), double-acting – DHWS-32



Gripping force FH per gripper jaw as a function of operating pressure and lever arm x – internal gripping (opening), double-acting – DHWS-40



Gripping force FH per gripper jaw at 0.6 MPa (6 bar, 87 psi) as a function of lever arm x and eccentricity a and b



Datasheet

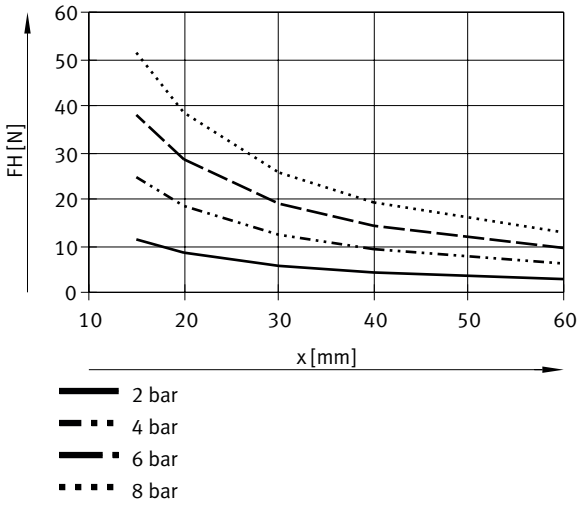
Gripping force FH per gripper jaw at 0.6 MPa (6 bar, 87 psi) as a function of lever arm x and eccentricity a and b

$x = \sqrt{a^2 + b^2} = \sqrt{20^2 + 25^2} = 32$ mm

The formula (on the left) must be used to calculate the lever arm x with eccentric gripping.
The gripping force FH can then be read from the graphs using the calculated value x.

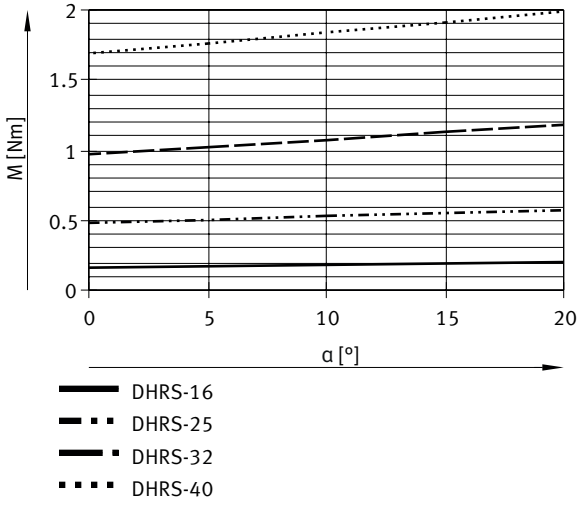
Calculation example:
Where:
Distance a = 20 mm
Distance b = 25 mm
To be determined:
The gripping force at 6 bar with a DHWS-16, used as an external gripper.

Gripping force FH per gripper jaw at 0.6 MPa (6 bar, 87 psi) as a function of lever arm x and eccentricity a and b



The graph gives a value of FH = 18 N for the gripping force.

Spring torque MF as a function of the opening angle



Datasheet

Determining the actual gripping torques MGrtotal for DHWS-...-NC as a function of the application

Depending on the requirement, the angle grippers with integrated spring, type DHWS-...-NC (closing gripping force backup) can be used as:
- Single-acting grippers
- Gripper with gripping force support and
- Grippers with gripping force backup

.

To calculate the available gripping torque MGrtotal (per gripper jaw), the gripping force FH and the spring torque MF must be combined accordingly.

MGr = FH * x

MGr = Gripping torque
FH = Gripping force
x = Lever arm

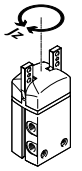
Determining the actual gripping torques MGrtotal for DHWS-...-NC as a function of the application – application

Single-acting:
- Gripping with spring force: MGrtotal = MF
- Gripping with pressure force: MGrtotal = MGr – MF

Gripping force support:
- Gripping with pressure and spring force: MGrtotal = MGr + MF

Gripping force retention
- Gripping with spring force: MGrtotal = MF

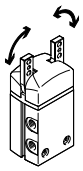
Mass moments of inertia



Mass moment of inertia of the gripper in relation to the central axis, without external gripper fingers, with no load.

Size	10	16		25		32		40	
Gripping force backup	None		Closing	None	Closing	None	Closing	None	Closing
Mass moment of inertia	0.03 kgcm²	0.14 kgcm²	0.15 kgcm²	0.62 kgcm²	0.64 kgcm²	1.6 kgcm²	1.63 kgcm²	3.81 kgcm²	3.87 kgcm²

Opening and closing times

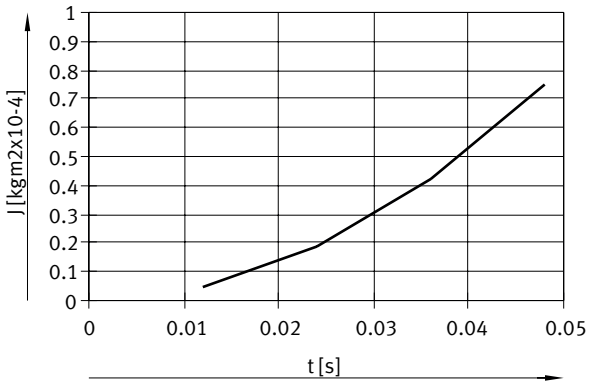


The indicated opening and closing times were measured at room temperature at an operating pressure of 0.6 MPa (6 bar, 87 psi) with a horizontally mounted gripper without additional gripper fingers.
The grippers must be throttled for masses that are higher than the specified unthrottled maximum mass per external gripper finger. Opening and closing times must then be adjusted accordingly.

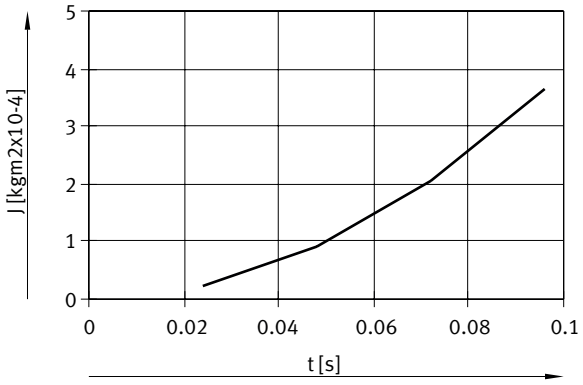
Size	10	16		25		32		40	
Gripping force backup	None		Closing	None	Closing	None	Closing	None	Closing
Min. opening time at 0.6 MPa (6 bar, 87 psi)	10 ms	44 ms	62 ms	64 ms	106 ms	46 ms	88 ms	63 ms	99 ms
Min. closing time at 0.6 MPa (6 bar, 87 psi)	22 ms	52 ms	36 ms	80 ms	59 ms	77 ms	55 ms	96 ms	69 ms

Datasheet

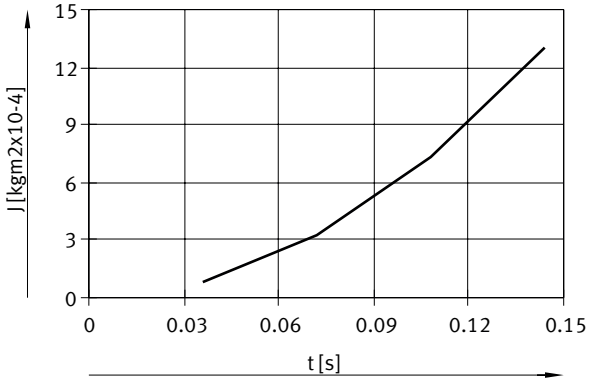
Opening and closing times t to be set as a function of mass moment of inertia of the gripper fingers with 0.6 MPa (6 bar, 87 psi) – DHWS-10



Opening and closing times T to be set as a function of mass moment of inertia of the gripper fingers with 0.6 MPa (6 bar, 87 psi) – DHWS-16

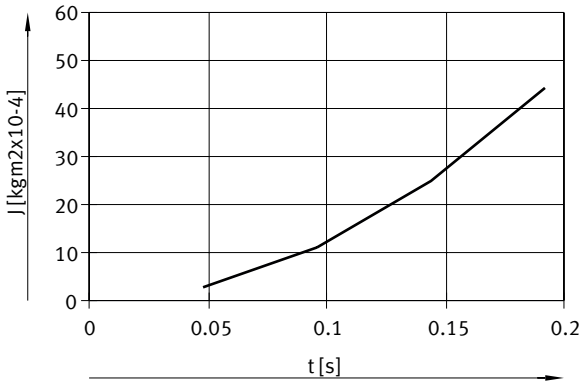


Opening and closing times T to be set as a function of mass moment of inertia of the gripper fingers with 0.6 MPa (6 bar, 87 psi) – DHWS-25

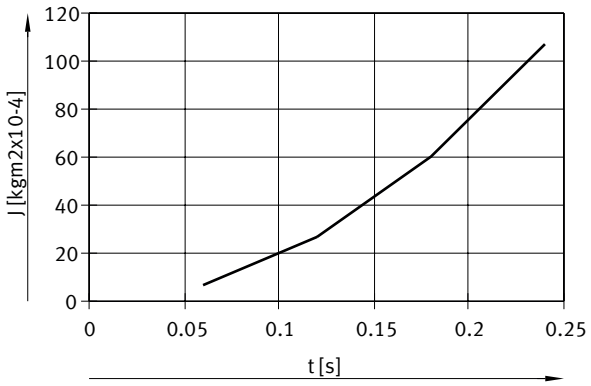


Datasheet

Opening and closing times T to be set as a function of mass moment of inertia of the gripper fingers with 0.6 MPa (6 bar, 87 psi) – DHWS-32

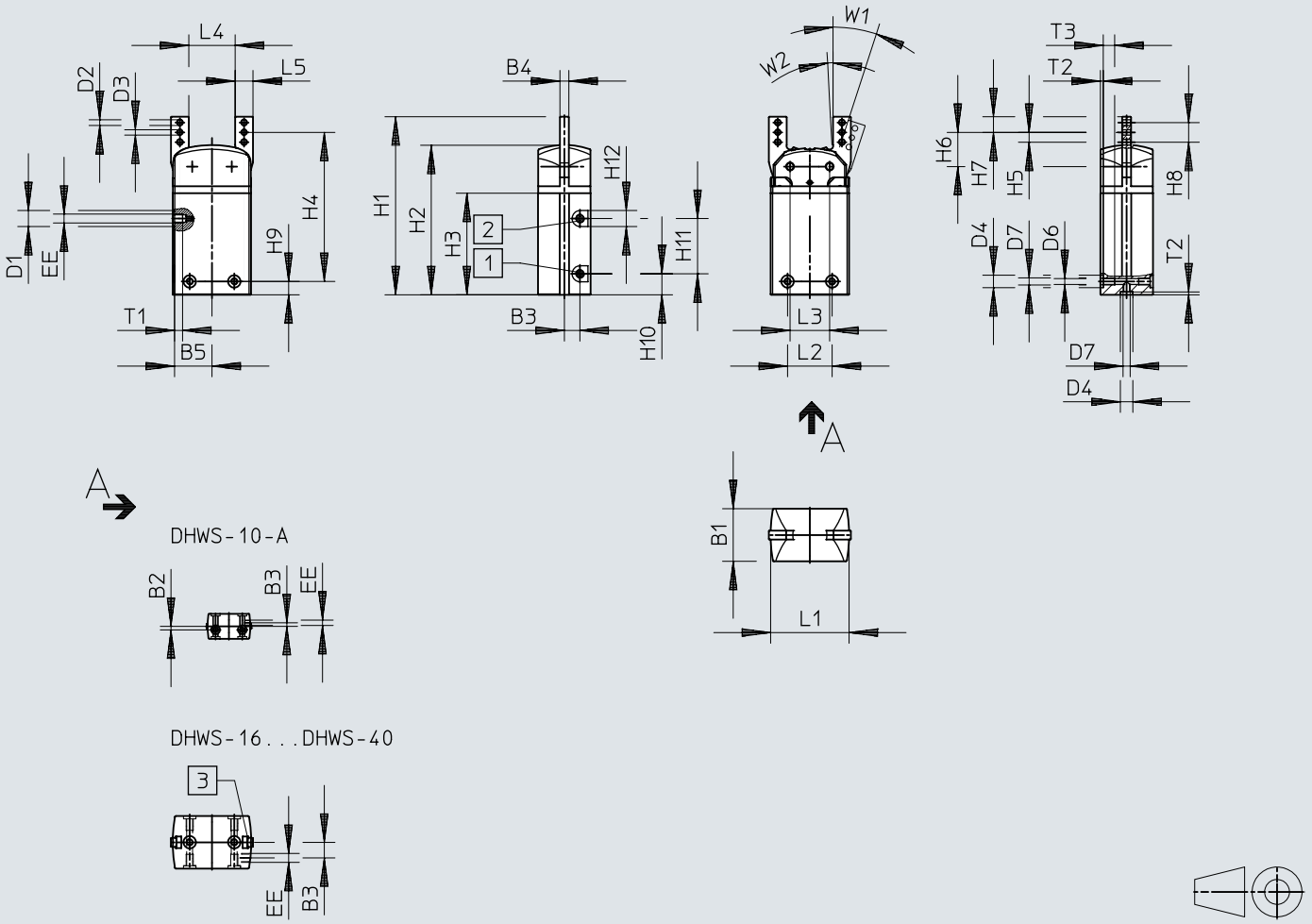


Opening and closing times T to be set as a function of mass moment of inertia of the gripper fingers with 0.6 MPa (6 bar, 87 psi) – DHWS-40



Dimensions

Dimensions – Angle gripper DHWS Download CAD data www.festo.com



[1] Open compressed air supply port
[2] Close compressed air supply port
[3] Slot for proximity switch

Dimensions

	B1 ±0,05	B2[1]	B3	B4 –0,03/ –0,05	B5	D1 ø	D2 ø ±0,1	D3 ø H8	D4 ø H8/h7	D6 ø +0,1	D7
DHWS-10	14	2	2	3	11,6	7	2,2	2	5	2,4	M3
DHWS-16	19	–	5,8	4	16	–	3,2	2,5	5	2,5	M3
DHWS-25	29,5	–	8,75	5	21	9	3,2	3	7	3,3	M4
DHWS-32	38	–	11	6	24	15	4,3	3	9	5,1	M6
DHWS-40	49	–	11	8	28,4	15	5,3	4	12	6,4	M8

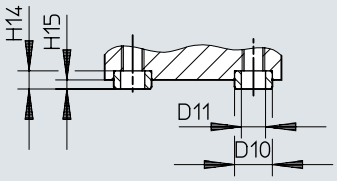
	EE	H1	H2	H3	H4 ±0,2	H5	H6 ±0,05	H7	H8	H9[2]	H10
DHWS-10	M3	56,3	46	30,8	38,25	3,5	10,95	5,75	7	12,3	8,8
DHWS-16	M3	81	67	45,5	66	4,5	15,5	7,5	9	7,5	12,25
DHWS-25	M5	100	84	57	83,7	5,5	19,2	8,8	11	7,5	11,8
DHWS-32	G1/8	116	96,2	65	100,5	6,5	22,5	11	13	11	20
DHWS-40	G1/8	129	108,4	71,5	99,5	7	24,5	12	14	17,5	9

	H11	H12	L1 ±0,05	L2[1]	L3 ±0,02	L4	L5 –0,02/ –0,05	T1 +0,5	T2 +0,1	T3 +1	W1 +3°/–1°	W2 ±1°
DHWS-10	16	7	24	15	12,4	14	5,5	3,5	1,2	–	18	3
DHWS-16	23	7	34	16	17	18	8	4,5	1,2	5,8	18	3
DHWS-25	31	9	44	25	22,2	26	10	4,5	1,6	6,4	18	3
DHWS-32	25	15	53	29	25,8	29	12	7,5	2,1	12,9	18	3
DHWS-40	46	15	59	33	30	32	15	6	2,6	13,4	18	3

1) Tolerance for centring hole ±0.02 mm Tolerance for thread ±0.1 mm
2) Tolerance for centring hole –0.05 mm/tolerance for thread ±0.1 mm

Dimensions

Dimensions – Angle gripper DHWS – mounting interface Download CAD data www.festo.com



[1] Centring sleeves ZBH for mounting the gripper (2 pieces included in the scope of delivery)

	D10 ø h7	D11 ø	H14 –0,2	H15 –0,3
DHWS-10	5	3,2	2,4	1,2
DHWS-16	5	3,2	2,4	1,2
DHWS-25	7	5,3	3	1,4
DHWS-32	9	6,4	4	1,9
DHWS-40	12	10,3	5	2,4

Ordering data

Double-acting, without compression spring

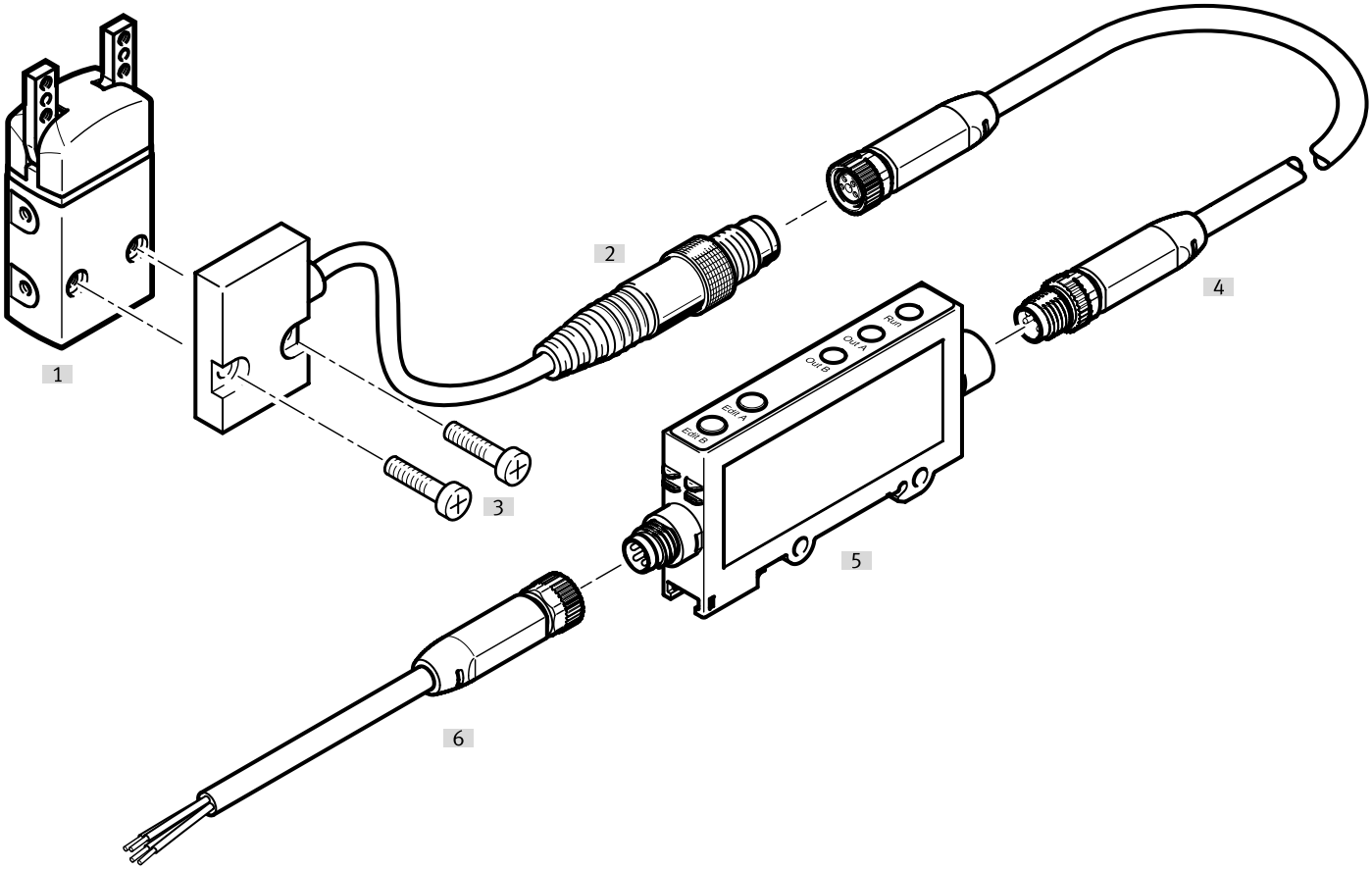
	Size	Product weight	Part no.	Type
	10	40 g	**1310177**	**DHWS-10-A**
	16	110 g	**1310178**	**DHWS-16-A**
	25	258 g	**1310180**	**DHWS-25-A**
	32	452 g	**1310182**	**DHWS-32-A**
	40	775 g	**1310184**	**DHWS-40-A**

Single-acting or with gripping force backup, closing

	Size	Product weight	Part no.	Type
	16	114 g	**1310179**	**DHWS-16-A-NC**
	25	265 g	**1310181**	**DHWS-25-A-NC**
	32	462 g	**1310183**	**DHWS-32-A-NC**
	40	790 g	**1310185**	**DHWS-40-A-NC**

Peripherals

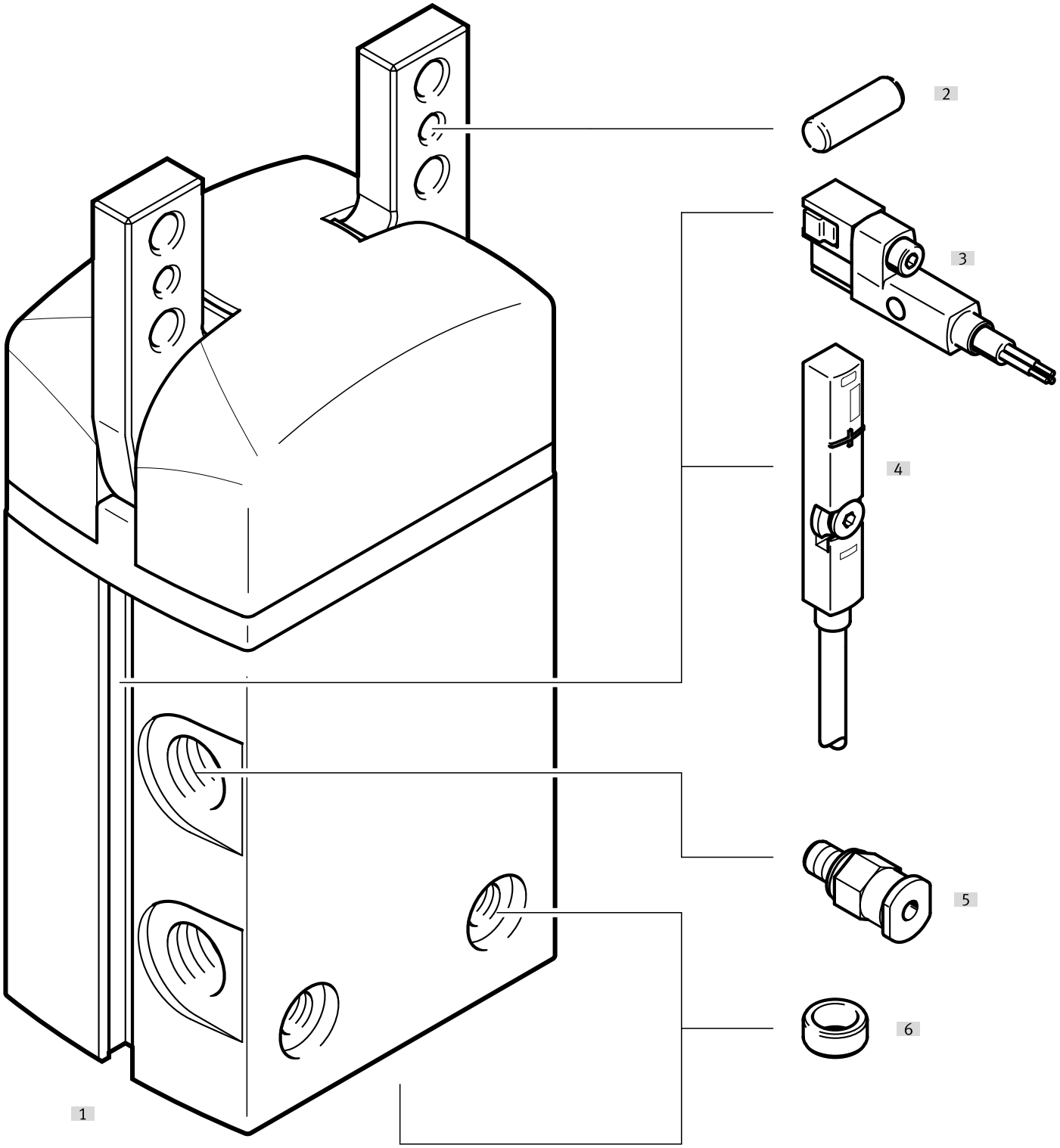
Peripherals overview DHWS-10



Accessories			→ Link
	Type/order code	Description	
[1]	Angle gripper DHWS	Double-acting	dhws
[2]	Position sensor SMH-S1	Adaptable and integrable sensors for sensing the piston position	23
[3]	Screws	For mounting the SMH-S1 position sensor on the gripper	dhws
[4]	Connecting cable NEBA	Connection between position sensor and signal converter	24
[5]	Signal converter SVE4	For signal evaluation for position sensor SMH-S1	23
[6]	Connecting cable NEBA	Connection between signal converter and controller	25
[7]	Adapter kit DHAA, HMSV, HAPG	Connecting plate between drive and gripper	dhaa
[8]	Proportional-pressure regulator VPPM	For infinitely variable adjustment of the gripping force	vppm

Peripherals

Peripherals overview DHWS-16 ... 40



Accessories			→ Link
	Type/order code	Description	
[1]	Angle gripper DHWS	Double-acting	dhws
[2]	Centring pin	For centring the gripper fingers on the gripper jaws	dhws
[3]	Proximity switch SMT-8G	• For sensing the piston position • Proximity switch does not project underneath the housing	24
[4]	Position transmitter SMAT-8M	Continuously senses the position of the piston. It has an analogue output with an output signal in proportion to the piston position	25

Peripherals

Accessories			→ Link
	Type/order code	Description	
[4]	Position transmitter SDAT	Continuously senses the position of the piston. It has an analogue output with an output signal in proportion to the piston position	25
[5]	Push-in fitting QS	For connecting tubing with standard O.D.	qs
[6]	Centring sleeve ZBH	• For centring the gripper when mounting • 2 centring sleeves are included in the scope of delivery of the gripper	23
[7]	Adapter kit DHAA, HMSV, HAPG	Connecting plate between drive and gripper	dhaa
[8]	Proportional-pressure regulator VPPM	For infinitely variable adjustment of the gripping force	vppm

Accessories

Centring sleeve ZBH-5

	Description	Material sleeve	Size of pack	Product weight	Part no.	Type
	For sizes 10, 16	Steel	10	1 g	**8146543**	**ZBH-5-B**

Centring sleeve ZBH-7

	Description	Material sleeve	Size of pack	Product weight	Part no.	Type
	For size 25	Steel	10	1 g	**8146544**	**ZBH-7-B**

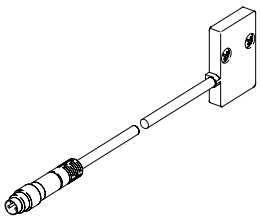
Centring sleeve ZBH-9

	Description	Material sleeve	Size of pack	Product weight	Part no.	Type
	For size 32	Steel	10	2 g	**8137184**	**ZBH-9-B**

Centring sleeve ZBH-12

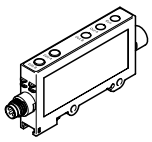
	Description	Material sleeve	Size of pack	Product weight	Part no.	Type
	For size 40	Steel	10	1 g	**8137185**	**ZBH-12-B**

Position sensor SMH-S1 for direct fastening, magnetic Hall – for size 10 Link smh

	Type of mounting [1]	Output signal	Electrical connection	Cable length	Part no.	Type
	Screwed onto gripper	Analogue	Plug M8, A-coded	0.5 m	**175711**	**SMH-S1-HGW10**

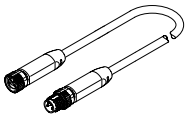
1) Installation note: To ensure the functionality of the position sensor, the cable outlet and the outlet of the compressed air tube must point in the same direction during installation.

Signal converter SVE4 – for size 10 Link sve

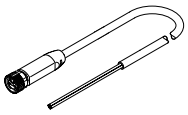
	analog input	Electrical connection (signal input)	Electrical connection (switching output)	Switching output	Part no.	Type
	Adapted for position sensors SMH-S1-HG	Socket M8x1, 4-pin	Plug M8x1, 4-pin	2xNPN	**544219**	**SVE4-HS-R-HM8-2N-M8**
				2xPNP	**544216**	**SVE4-HS-R-HM8-2P-M8**

Accessories

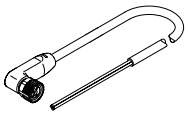
Connecting cables NEBA, straight – connection between position sensor and signal converter

	Electrical connection 1, connector system	Electrical connection 2, connector system	Electrical connection 2, number of connections/ cores	Cable length	Part no.	Type
	M8x1, A-coded, to EN 61076-2-104	M8x1, A-coded to EN 61076-2-104	4	2.5 m	**8078295**	**NEBA-M8G4-U-2.5-N-M8G4**

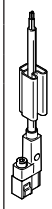
Connecting cables NEBA, straight – connection between signal converter and controller

	Electrical connection 1, connector system	Electrical connection 2, connector system	Electrical connection 2, number of connections/ cores	Cable length	Part no.	Type
	M8x1, A-coded, to EN 61076-2-104	Open end	4	2.5 m	**8078227**	**NEBA-M8G4-U-2.5-N-LE4**
				5 m	**8078228**	**NEBA-M8G4-U-5-N-LE4**

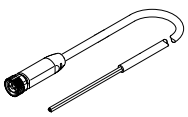
Connecting cables NEBA, angled – connection between signal converter and controller

	Electrical connection 1, connector system	Electrical connection 2, connector system	Electrical connection 2, number of connections/ cores	Cable length	Part no.	Type
	M8x1, A-coded, to EN 61076-2-104	Open end	4	2.5 m	**8078233**	**NEBA-M8W4-U-2.5-N-LE4**
				5 m	**8078234**	**NEBA-M8W4-U-5-N-LE4**

Proximity switch SMT-8G for T-slot, magneto-resistive – for sizes 16 ... 40 Link smt

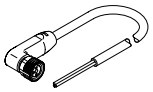
	Type of mounting	Switching output	Electrical connection	Cable length	Part no.	Type
	Clamped in T-slot, Inserted into the slot lengthwise	3-wire NPN N/O contact	Open end	2.5 m	**8065028**	**SMT-8G-NS-24V-E-2,5Q-OE**
			Plug M8, A-coded	0.3 m	**8065027**	**SMT-8G-NS-24V-E-0,3Q-M8D**
		3-wire PNP N/O contact	Open end	2.5 m	**547859**	**SMT-8G-PS-24V-E-2,5Q-OE**
			Plug M8, A-coded	0.3 m	**547860**	**SMT-8G-PS-24V-E-0,3Q-M8D**

Connecting cables NEBA, straight

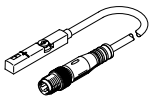
	Electrical connection 1, connector system	Electrical connection 2, connector system	Electrical connection 2, number of connections/ cores	Cable length	Part no.	Type
	M8x1, A-coded, to EN 61076-2-104	Open end	3	2.5 m	**8078223**	**NEBA-M8G3-U-2.5-N-LE3**
				5 m	**8078224**	**NEBA-M8G3-U-5-N-LE3**

Accessories

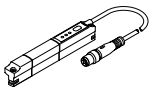
Connecting cables NEBA, angled

	Electrical connection 1, connector system	Electrical connection 2, connector system	Electrical connection 2, number of connections/ cores	Cable length	Part no.	Type
	M8x1, A-coded, to EN 61076-2-104	Open end	3	2.5 m	**8078230**	**NEBA-M8W3-U-2.5-N-LE3**
				5 m	**8078231**	**NEBA-M8W3-U-5-N-LE3**

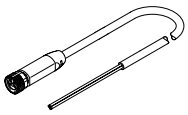
Position transmitter SMAT-8M for T-slot, plug M8, A-coded – for size 16 ... 40 Link smat

	Sensing range	Analogue output	Electrical connection 1, number of connections/ cores	Cable length	Part no.	Type
	52 mm	0 - 10 V	4	0.3 m	**553744**	**SMAT-8M-U-E-0,3-M8D**

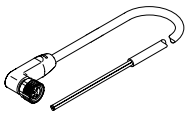
Position transmitter SDAT for T-slot, M8 plug, A-coded – for size 32 ... 40 Link sdat

	Sensing range	Analogue output	Electrical connection 1, number of connections/ cores	Cable length	Part no.	Type
	0 ... 50.000 mm	4 - 20 mA	4	0.3 m	**1531265**	**SDAT-MHS-M50-1L-SA-E-0.3-M8**

Connecting cables NEBA, straight

	Electrical connection 1, connector system	Electrical connection 2, connector system	Electrical connection 2, number of connections/ cores	Cable length	Part no.	Type
	M8x1, A-coded, to EN 61076-2-104	Open end	4	2.5 m	**8078227**	**NEBA-M8G4-U-2.5-N-LE4**
				5 m	**8078228**	**NEBA-M8G4-U-5-N-LE4**

Connecting cables NEBA, angled

	Electrical connection 1, connector system	Electrical connection 2, connector system	Electrical connection 2, number of connections/ cores	Cable length	Part no.	Type
	M8x1, A-coded, to EN 61076-2-104	Open end	4	2.5 m	**8078233**	**NEBA-M8W4-U-2.5-N-LE4**
				5 m	**8078234**	**NEBA-M8W4-U-5-N-LE4**