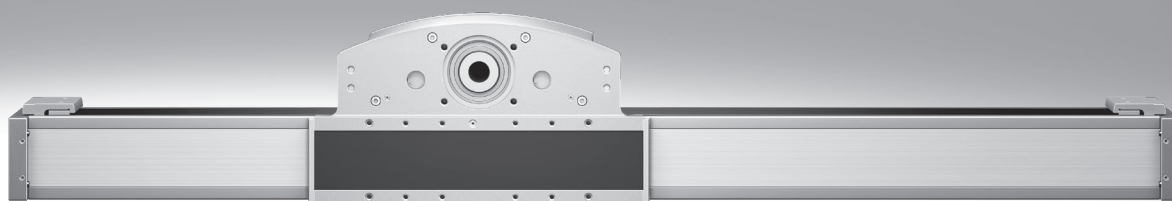


Cantilever axes ELCC

FESTO

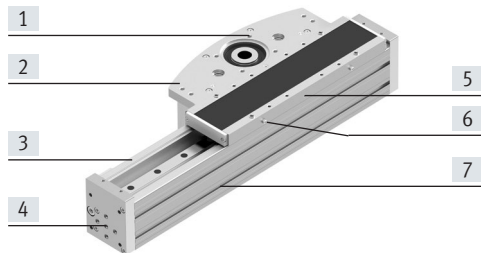


Key features

At a glance

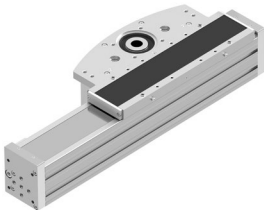
- High rigidity thanks to innovative design principle
- Very small moving mass
- Able to move high loads of up to 100 kg vertically
- Optionally with NSF-H1 lubricant for the food industry.
- Toothed belt material can be selected from:
 - Chloroprene rubber for long service life
 - Uncoated PU for the food zone
 - PU coated with steel reinforcement cords for long service life and resilience to certain cooling lubricants

The technology in detail



- [1] Interface for motor mounting
- [2] Drive head
- [3] Cantilever profile
- [4] Front end
- [5] Connection for clamping unit or sealing air (available on both sides)
- [6] Connection for lubrication hole (available on both sides)
- [7] Mounting slot for accessories

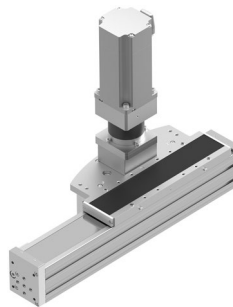
Protection against particles



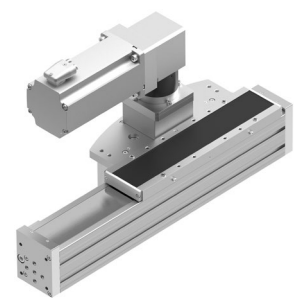
- Stainless steel cover strip provides basic protection for the guide

Motor attachment (can also be mounted underneath)

Axial



With right-angle gear unit



Additional slide



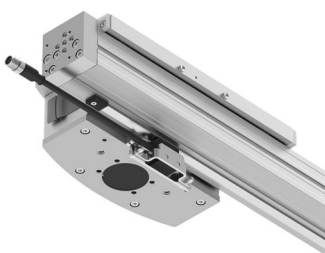
- Rigidity and load-bearing capacity are increased by having twice as many roller carriages and a greater distance between bearings

Clamping unit



- For holding loads securely (frictional locking)
- Integrated into the axis so it does not protrude
- Acts directly on the guide (in any position)
- Can also be used for emergency braking operations

Displacement encoder



- The position is detected incrementally and without contact
- To improve absolute accuracy
- 2-channel solutions are possible together with the motor encoder and a safety relay unit
- For sizes 60/70 the displacement encoder system is attached on the outside; for sizes 90/110 it is integrated underneath the toothed belt

Sealing air connection

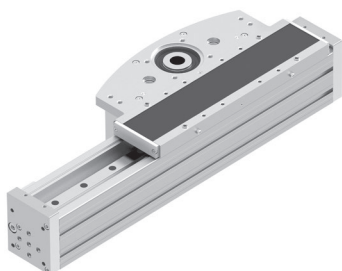


- Application of negative pressure minimises the dispersal of abraded particles into the environment
- Application of positive pressure prevents dirt from getting into the axis
- Cannot be used in combination with the clamping unit

Key features

Complete system comprising toothed belt axis, motor, motor controller and motor mounting kit

Cantilever axis



Motor



Servo motor:
EMMT-AS
Stepper motor:
EMMB-ST, EMMT-ST



Note

A range of specially adapted complete solutions is available for the cantilever axis ELCC and the motors.

Servo drives



Servo drive:
CMMT-AS
Servo drive for extra-low voltage:
CMMT-ST

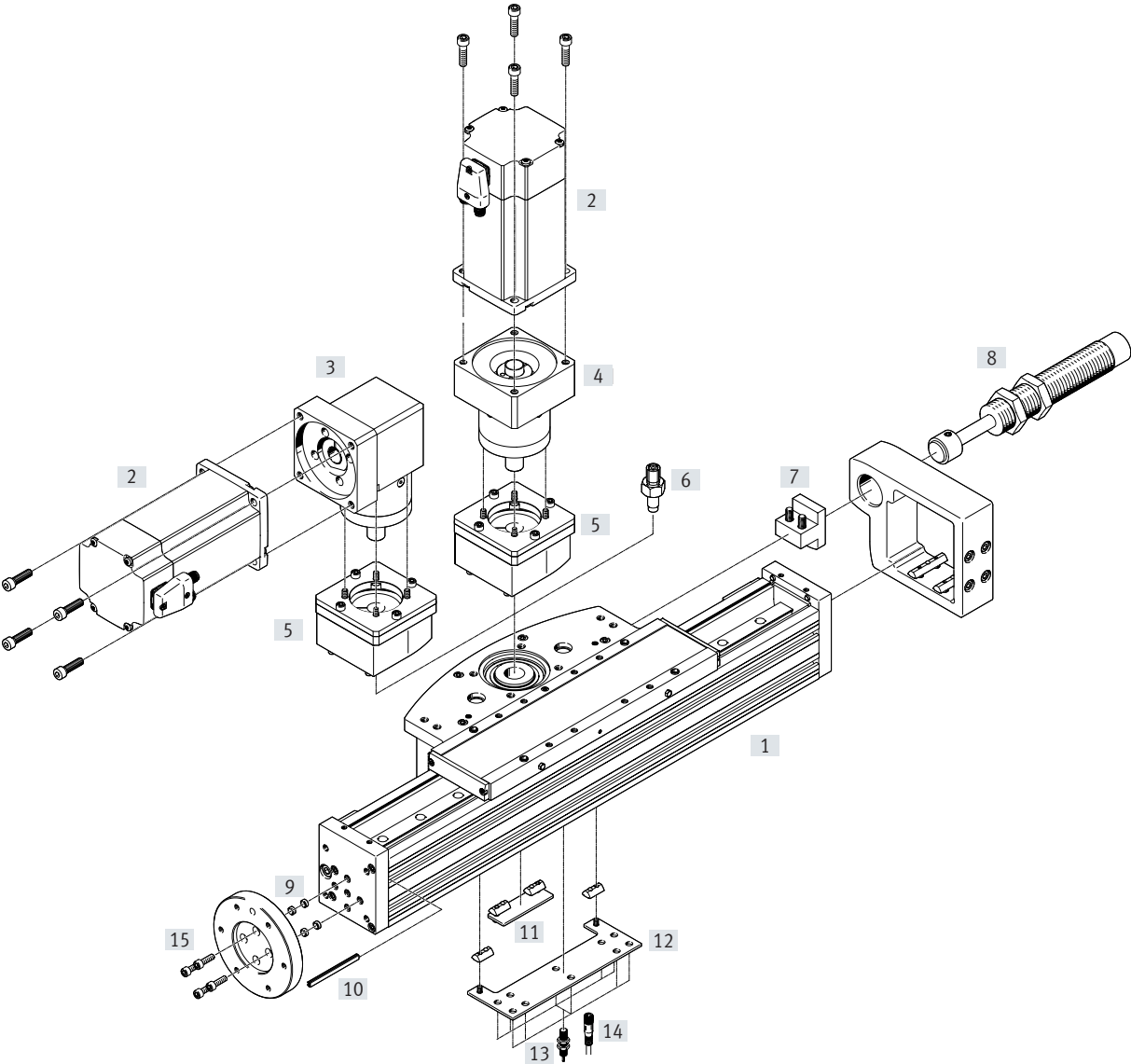
Motor mounting kit



Kit consists of:

- Motor flange
- Coupling housing
- Coupling
- Screws

Peripherals overview



Peripherals overview

Accessories		
	Type	Description
		→ Page/Internet
[1]	Cantilever axis ELCC	Electric axis
[2]	Motor EMMT	Motors specially matched to the axis, with or without gear unit, with or without brake
[3]	Right-angle gear unit EMGA-...-A	With gear ratio $i = 3$ and $i = 5$
[4]	Gear unit EMGA-...-A	With gear ratio $i = 3$ and $i = 5$
[5]	Axial kit EAMM	For axial motor mounting (comprising coupling, coupling housing and motor flange)
[6]	Drive shaft adapter EAMB	- Can be used as an alternative interface, as required - No drive shaft adapter is required for the axis/motor combinations → page 25
[7]	Shock absorber retainer DAYP-E21	For mounting a shock absorber on the axis
[8]	Shock absorber YSR	- Protects the axis from damage in the event of power failure or unintended lowering - Max. impact energy must be observed
[9]	Centring pin/sleeve ZBS, ZBH	- For centring attachments on the front end - For mounting the drive head
[10]	Slot cover ABP	For protection against contamination
[11]	Switch lug DASI-E21-SL	For sensing the slide position
[12]	Sensor bracket DASI-E21-SR	For mounting the inductive proximity switches (round design) on the axis
[13]	Proximity switch, M8 SIEN-M8	Inductive proximity switch, round design
[14]	Connecting cable NEBA	For proximity switch SIEN-M8
[15]	Adapter kit DHAA-R	For interface to ISO 9409-1:2004
–	Adapter kit DHAA	- Drive/drive connections - Drive/gripper connections
–	Slot nut NST	For mounting attachments
–	Connecting shaft KSK	- For torsion-resistant transmission of torques - For slip-free transmission of feed rates - To operate two cantilever axes in parallel using one motor

Type codes

001	Series	
ELCC	Cantilever axis	
002	Drive system	
TB	Toothed belt	
003	Guide	
KF	Recirculating ball bearing guide	
004	Size	
60	60	
70	70	
90	90	
110	110	
005	Stroke	
...	50 ... 2000	
006	Stroke reserve	
...	0 ... 999	
007	Additional slide	
	None	
ZR	1 slide right	
ZL	1 slide left	
ZLC	1 slide on left, with clamping unit	
ZRC	1 slide on right, with clamping unit	

008	Protection against particles	
P0	Without strip cover	
P9	With cover strip	
009	Additional characteristics	
	None	
F1	Food-safe according to supplementary information on materials	
010	Material of toothed belt	
CR	Chloroprene rubber	
PU1	Uncoated PU, FDA-compliant	
PU2	Coated PU	
011	Displacement encoder	
	None	
M1	With displacement encoder, incremental, resolution 2.5 µm	
012	Clamping unit	
	None	
C	Attached	
013	Operating instructions	
	With operating instructions	
DN	No operating instructions	

Datasheet



-  Size
 60 ... 110
-  Stroke length
 50 ... 2000 mm



General technical data					
Size		60	70	90	110
Design		Electromechanical cantilever axis			
Guide		Recirculating ball bearing guide			
Mounting position		Any			
Working stroke ¹⁾	[mm]	50 ... 1300	50 ... 1500	50 ... 2000	50 ... 2000
Max. feed force F _x	[N]	300	600	1200	2500
Max. no-load torque ²⁾	[Nm]	0.6	1.2	2.5	4
Max. driving torque	[Nm]	5.2	10.4	33	90
Max. speed	[m/s]	5			
Max. acceleration	[m/s ²]	50			30
Repetition accuracy	[mm]	±0.05			

1) Longer strokes on request

2) At 0.2 m/s

Operating and environmental conditions		
Ambient temperature ¹⁾	[°C]	−10 ... +60
Degree of protection		IP20
Duty cycle	[%]	100

1) Note operating range of proximity switches

Weight [g]				
Size	60	70	90	110
Basic weight with 0 mm stroke				
ELCC-...	4146	7960	15713	27299
Dimensions of additional slide, clamping unit, belt cover and distance measuring system				
ELCC-...-ZL/ZR	1907	4316	6718	11713
ELCC-...-C	–	278	416	772
ELCC-...-P9	76	126	128	176
ELCC-...-M1	196	201	218	243
Moving mass with 0 mm stroke				
ELCC-...	1636	3210	5487	10017
ELCC-...-ZL/ZR (additional)	1102	2306	3721	6936
Additional weight per 10 mm stroke				
ELCC-...	38	63	97	148

Toothed belt					
Size		60	70	90	110
Pitch	[mm]	3	3	5	8
Elongation ¹⁾					
ELCC-...-CR	[%]	0.17	0.22	0.14	0.17
ELCC-...-PU1/PU2	[%]	0.07	0.08	0.06	–
Width	[mm]	30	50	75	100
Effective diameter	[mm]	30.558	30.558	50.93	68.755
Feed constant	[mm/rev]	96	96	160	216

1) At max. feed force

Datasheet

Mass moments of inertia					
Size		60	70	90	110
J_0	[kg mm ²]	594	1063	5518	15710
J_H per metre stroke	[kg mm ² /m]	887	1471	6290	17491
J_L per kg payload	[kg mm ² /Kg]	233	233	648	1182

The mass moment of inertia J_A of the entire axis is calculated as follows:

Basic design

$$J_A = J_0 + J_H \times l [m] + J_L \times m_N [kg]$$

With gear unit

$$J_A = J_G + \frac{J_0 + J_H \cdot l [m] + J_L \cdot m_N [kg]}{i^2}$$

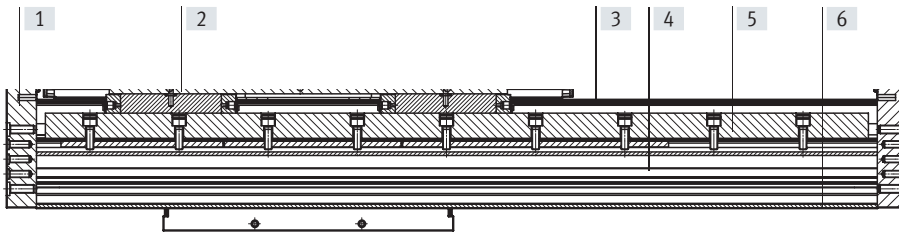
J_G = Mass moment of inertia of the gear unit

l = Working stroke

m_N = Payload

Materials

Sectional view



Axis		60	70	90	110
Size					
[1] End cap		Anodised wrought aluminium alloy			
[2] Drive head		Anodised wrought aluminium alloy			
[3] Cover strip		Stainless steel strip, non-corroding			
[4] Toothed belt					
	ELCC-...-CR	Polychloroprene with glass cord and nylon coating			
	ELCC-...-PU1	Polyurethane with steel cord (for food zone)			
	ELCC-...-PU2	Polyurethane with steel cord and fabric coating			
[5] Guide rail		Rolled steel, corrotec coated			
[6] Profile		Anodised wrought aluminium alloy			
– Slide		Anodised cast aluminium			
	Note on materials	RoHS-compliant			
	LABS (PWIS) conformity	VDMA24364 zone III			

Datasheet

Technical data – Displacement encoder				
Size	60	70	90	110
Resolution	[μm] 2.5			
Max. travel speed with displacement encoder	[m/s] 4			
Encoder signal	5 V TTL; A/A, B/B; reference signal (N/N) cyclically every 5 mm (zero pulse)			
Signal output	Line driver, alternating, resistant to sustained short circuit			
Electrical connection	8-pin plug connector, round design, M12			
Cable length	[mm] 160	160	45	25

Operating and environmental conditions – Displacement encoder	
Ambient temperature	[°C] -10 ... +70
Degree of protection	IP64
CE marking (see declaration of conformity)	To EU EMC Directive ¹⁾

1) For information about the area of use, see the EC declaration of conformity at: www.festo.com/sp → Certificates.

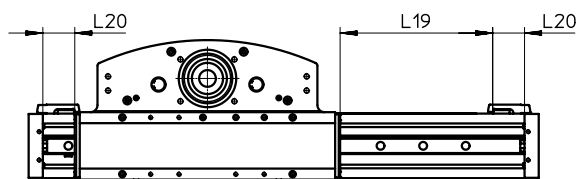
If the devices are subject to usage restrictions in residential, commercial or light-industrial environments, further measures for the reduction of the emitted interference may be necessary.

Technical data – Clamping unit			
Size	70	90	110
Pneumatic connection	M5		
Clamping type	Clamping via spring force, release via compressed air		
Static holding force	[N] 450	550	850
With opening pressure	[bar] 4	4	4
Max. number of emergency braking manoeuvres ¹⁾ with energy per emergency braking	[J] 1000 30	1000 30	1000 30
Tried-and-tested component	In accordance with EN ISO 13849-1:2023		

1) Emergency braking means braking of the moving mass, e.g. in case of power failure of the system.

Operating and environmental conditions – Clamping unit	
Operating medium	Compressed air to ISO 8573-1:2010 [7:4:4]
Operating pressure	[bar] 4 ... 6.5
Ambient temperature	[°C] -10 ... +60

Stroke reserve



L19 = Nominal stroke

L20 = Stroke reserve

- The stroke reserve is a safety distance from the mechanical end position and is not used in normal operation
- The sum of the nominal stroke and 2x stroke reserve must not exceed the maximum permissible working stroke
- The stroke reserve length can be freely selected
- The stroke reserve is defined via the "stroke reserve" characteristic in the modular product system.

Example:

Type ELCC-TB-KF-70-500-20H-...

Nominal stroke = 500 mm

2x 20 mm stroke reserve = 40 mm

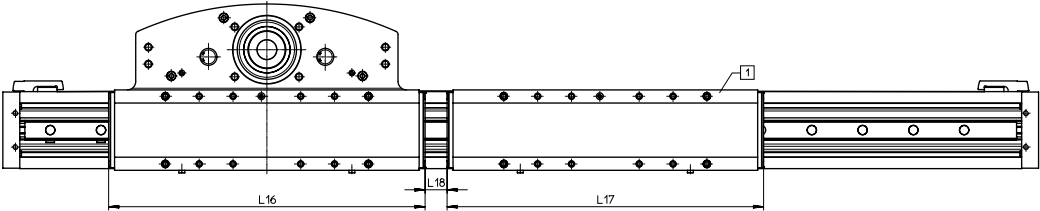
Working stroke = 540 mm

(540 mm = 500 mm + 2x 20 mm)

Datasheet

Working stroke reduction
For axis ELCC with additional slide ZL/ZR

For a cantilever axis with additional slide, the working stroke is reduced by the length of the additional slide and the distance between the two slides



- L16 = Slide length
- L17 = Additional slide length
- L18 = Distance between the two slides
- [1] Additional slide

Example:
Type ELCC-TB-KF-70-1500-...-ZR
Working stroke without
additional slide = 1500 mm
L18 = 50 mm
L17 = 356 mm
Working stroke with additional slide = 1094 mm
(1500 mm – 50 mm – 356 mm)

Dimensions – Additional slide					
Size		60	70	90	110
Length L17	[mm]	280	356	374	458
Min. distance between the slides L18					
ELCC-...-P0	[mm]	≥ 5	≥ 5	≥ 5	≥ 5
ELCC-...-P9	[mm]	≥ 50	≥ 50	≥ 50	≥ 50

Datasheet

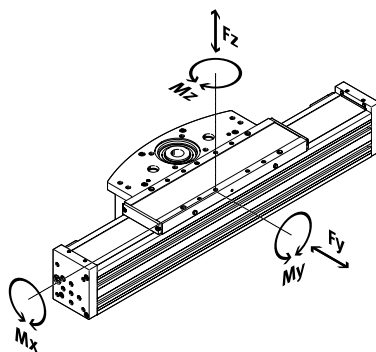
Characteristic load values of the axis in slide operation



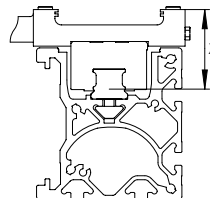
In slide operation, the profile is fixed and mounted in such a way that it does not sag.

The indicated forces and torques refer to the centre of the guide. The point of application of force is the point where the centre of the guide and the longitudinal centre of the slide intersect.

These values must not be exceeded during dynamic operation. Special attention must be paid to the deceleration phase.



Distance from the slide surface to the centre of the guide



Distance from the slide surface to the centre of the guide

Size	60	70	90	110
Dimension x [mm]	29.9	39.1	43.8	54.0

Max. permissible forces and torques for a service life of 5000 km in slide operation

Size	60	70	90	110
$F_{y\max}$ [N]	4200	9600	13900	20600
$F_{z\max}$ [N]	4100	9400	13500	20000
$M_{x\max}$ [Nm]	35	105	165	315
$M_{y\max}$ [Nm]	290	825	1300	2365
$M_{z\max}$ [Nm]	285	795	1230	2285



Note

For a guide system to have a service life of 5000 km, the load comparison factor must have a value of $f_v < 1$, based on the maximum permissible forces and torques for a service life of 5000 km.

If the axis is subjected to several of the indicated forces and torques at the same time, the following equation must be satisfied in addition to the indicated maximum loads:

Calculating the load comparison factor:

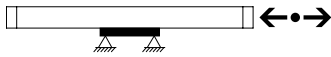
$$f_v = \frac{|F_{y1}|}{F_{y2}} + \frac{|F_{z1}|}{F_{z2}} + \frac{|M_{x1}|}{M_{x2}} + \frac{|M_{y1}|}{M_{y2}} + \frac{|M_{z1}|}{M_{z2}} \leq 1$$

F_1/M_1 = dynamic value

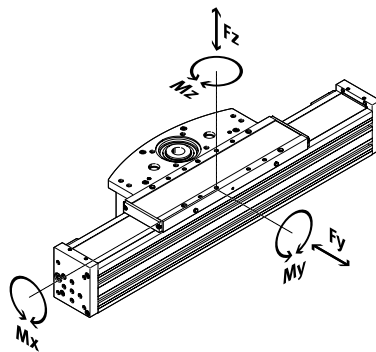
F_2/M_2 = maximum value

Datasheet

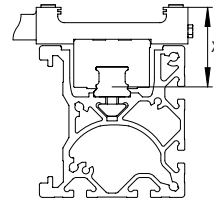
Characteristic load values of the axis in cantilever operation



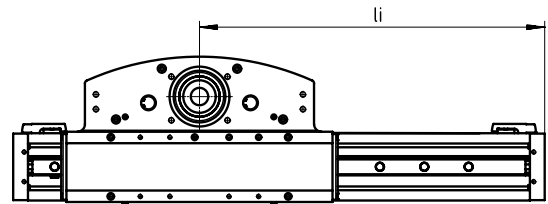
In cantilever operation, the axis is subjected to a higher load because of deflection. The torques are thus reduced in comparison to the slide operation. The indicated forces and torques refer to the centre of the guide. The point of application of force is the point where the centre of the guide and the longitudinal centre of the slide intersect. These values must not be exceeded during dynamic operation. Special attention must be paid to the deceleration phase.



Distance from the slide surface to the centre of the guide



Axis position



Distance from the slide surface to the centre of the guide

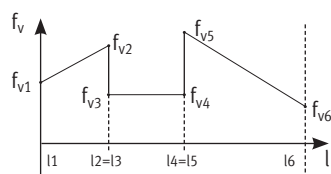
Size	60	70	90	110
Dimension x [mm]	29.9	39.1	43.8	54.0

Max. permissible forces and torques for a service life of 5000 km in cantilever operation

Size	60	70	90	110
Fyperm. [N]	4200	9600	13900	20600
Vehiclepermissible. [N]	4100	9400	13500	20000
Mxpermissible. [Nm]	20	50	75	180
Myperm. [Nm]	110	240	350	885
Mzadmissible. [Nm]	90	190	295	615

Step 1:

Calculating the load comparison factor f_{vi} for the different axis positions li



$$f_{vi} = \frac{|F_{y1}|}{F_{y2}} + \frac{|F_{z1}|}{F_{z2}} + \frac{|M_{x1}|}{M_{x2}} + \frac{|M_{y1}|}{M_{y2}} + \frac{|M_{z1}|}{M_{z2}}$$

$$f_{vi} = f_{v1}, f_{v2}, f_{v3}, f_{v4}, f_{v5}, f_{v6}$$

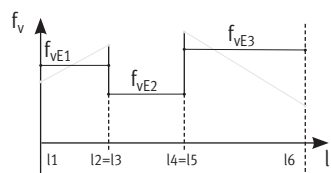
If all $f_{vi} \leq 1$, it can be assumed, for the purpose of simplicity, that:

Total load comparison factor f_{vG} corresponds to the largest f_{vi} and steps 2-3 can be omitted.

If any $f_{vi} > 1$, the precise total load comparison factor f_{vG} should be calculated using steps 2 and 3.

Step 2:

Calculating the substitute load comparison factors for the different partial strokes f_{vEi}



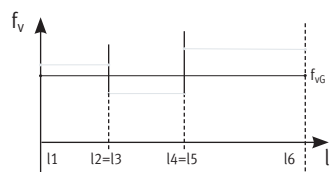
$$f_{vEi} = \sqrt[3]{\frac{(f_{vi} + f_{vi+1}) \cdot (f_{vi}^2 + f_{vi+1}^2)}{4}}$$

$$f_{vEi} = f_{vE1}, f_{vE2}, f_{vE3}$$

f_{vEi} = Substitute load comparison factor for partial stroke 1 l_1 to l_2 = Partial stroke 1

Step 3:

Calculating the load comparison factor f_{vG} for the total stroke



$$f_{vG} = \sqrt[3]{\sum \frac{f_{vEi}^3 \cdot (l_{i+1} - l_i)}{l_{ges}}}$$

f_{vG} = Load comparison factor for the total stroke

Step 4:

Calculating the service life

$$L = \frac{5000 \text{ km}}{f_{vG}^3}$$

Datasheet

Calculating the service life

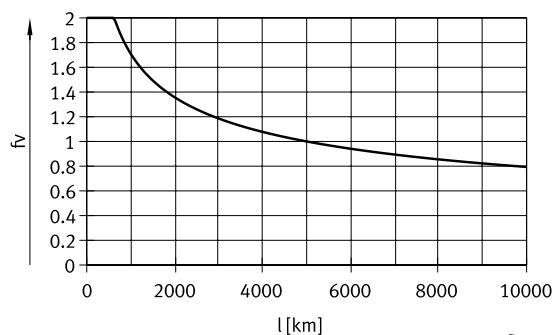
The service life of the guide depends on the load. To be able to make a statement as to the service life of the guide, the graph below plots the total load comparison factor f_{vE} against the service life.

These values are only theoretical. With an overall load comparison factor f_{vG} greater than 1.5, it is essential to consult your local contact at Festo.

Total load comparison factors f_{vG} as a function of service life

Example:

A user wants to move an X kg load. Using the formula (→ page 11/12) gives a value of 1.5 for the total load comparison factor f_{vG} . According to the graph, the guide has a service life of approx. 1500 km.



Note

Engineering software
Electric Motion Sizing
www.festo.com/x/electric-motion-sizing

The engineering software can be used to calculate the guide workload for a service life of 5000 km.

Comparison of the characteristic load values for 5000 km with dynamic forces and torques of recirculating ball bearing guides

The characteristic load values of the bearing guides are standardised to ISO and JIS using dynamic and static forces and torques. These forces and torques are based on an expected service life of the guide system of 100 km to ISO or 50 km to JIS.

As the characteristic load values are dependent on the service life, the maximum permissible forces and torques for a 5000 km service life cannot be compared with the dynamic forces and torques of bearing guides to ISO/JIS.

To make it easier to compare the guide capacity of cantilever axes ELCC with bearing guides, the table below lists the theoretically permissible forces and torques for a calculated service life of 100 km. This corresponds to the dynamic forces and torques to ISO.

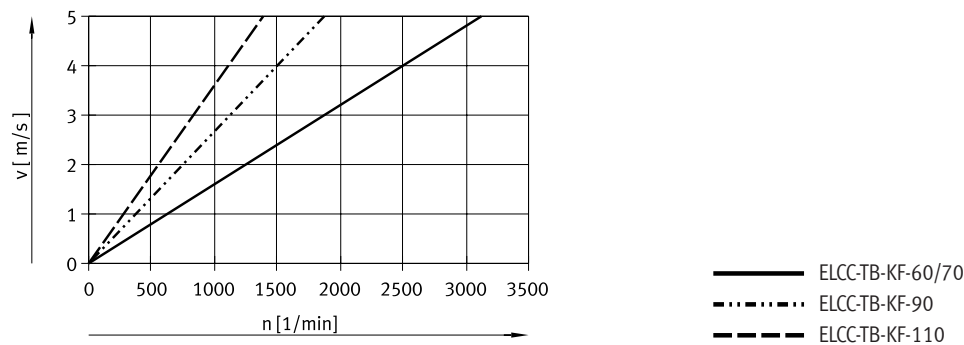
These 100 km values have been calculated mathematically and are only to be used for comparing with dynamic forces and torques to ISO. The drives must not be loaded with these characteristic values as this could damage the axes.

Max. permissible forces and torques for a theoretical service life of 100 km (from a guide perspective only)

Size		60	70	90	110
$F_{y_{max}}$	[N]	17101	39712	57255	84489
$F_{z_{max}}$	[N]	16410	37901	54354	80725
$M_{x_{max}}$	[Nm]	138	401	643	1221
$M_{y_{max}}$	[Nm]	1126	3138	4838	8982
$M_{z_{max}}$	[Nm]	1086	2954	4548	8488

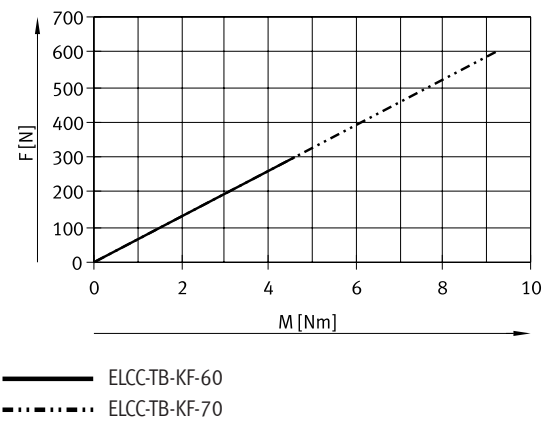
Datasheet

Speed v as a function of rotational speed n

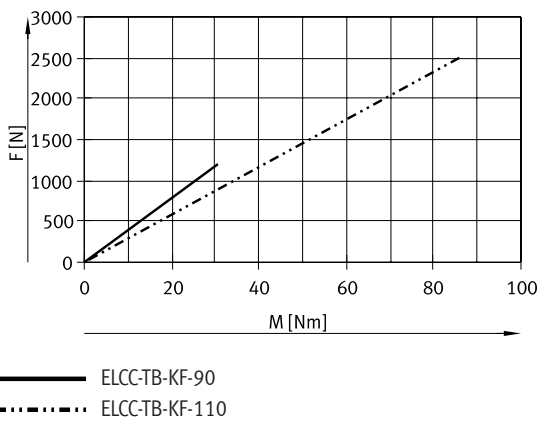


Theoretical feed force F as a function of input torque M

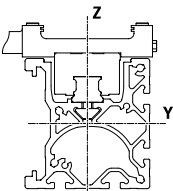
Size 6 0/70



Size 9 0/110



Second moment of area

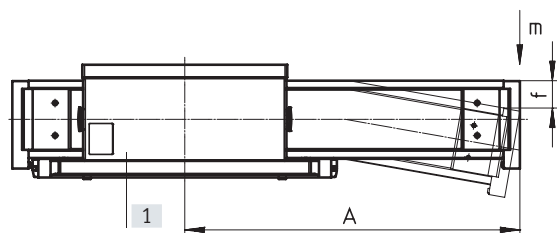


Size		60	70	90	110
I_y	[mm ⁴]	240.60×10^3	959.74×10^3	2.67×10^6	6.83×10^6
I_z	[mm ⁴]	304.21×10^3	928.74×10^3	2.05×10^6	4.93×10^6

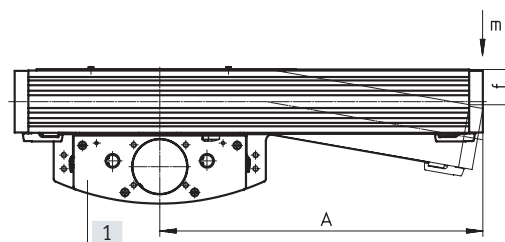
Datasheet

Deflection f as a function of the cantilever extension A and the payload m

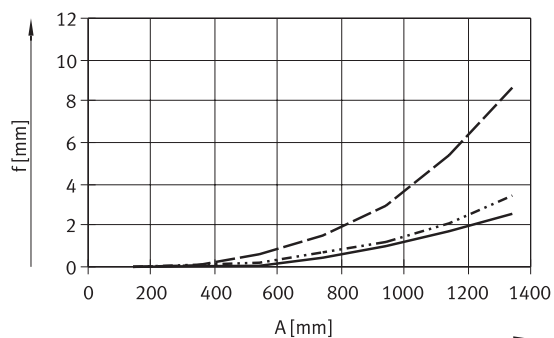
Interface for drive head [1], horizontal



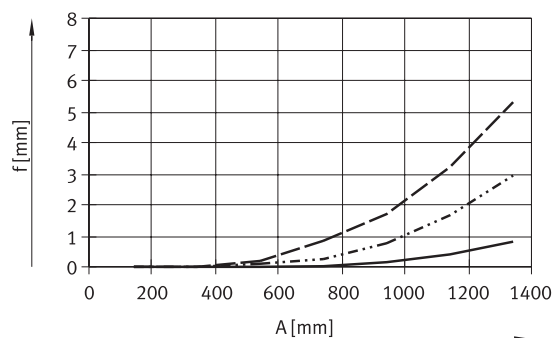
Interface for drive head [1], vertical



Size 60

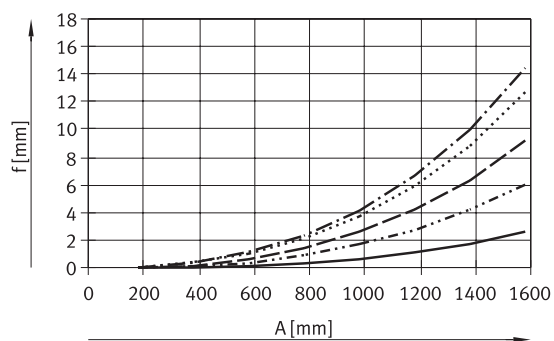


— $m = 0 \text{ kg}$
 $m = 5 \text{ kg}$
 - - - $m = 10 \text{ kg}$

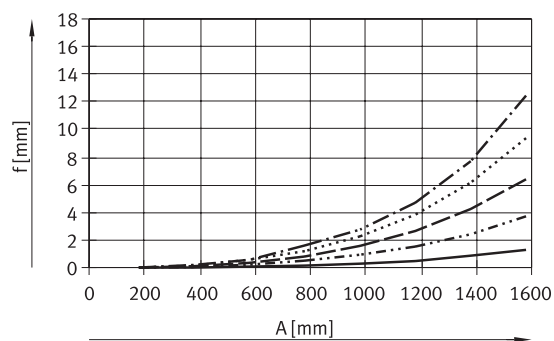


— $m = 0 \text{ kg}$
 $m = 5 \text{ kg}$
 - - - $m = 10 \text{ kg}$

Size 70



— $m = 0 \text{ kg}$
 $m = 10 \text{ kg}$
 - - - $m = 20 \text{ kg}$
 - · - · $m = 30 \text{ kg}$
 - - - - $m = 35 \text{ kg}$

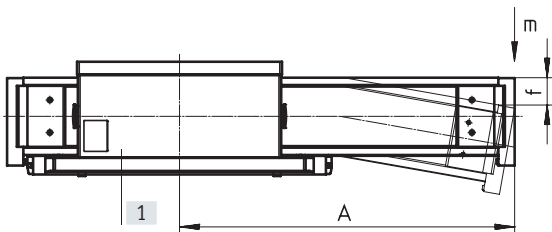


— $m = 0 \text{ kg}$
 $m = 10 \text{ kg}$
 - - - $m = 20 \text{ kg}$
 - · - · $m = 30 \text{ kg}$
 - - - - $m = 35 \text{ kg}$

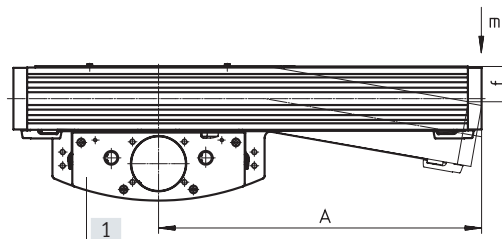
Datasheet

Deflection f as a function of the cantilever extension A and the payload m

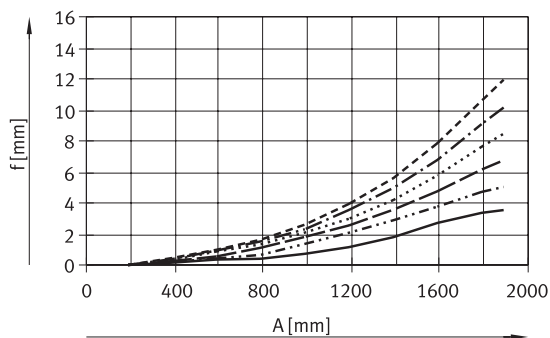
Interface for drive head [1], horizontal



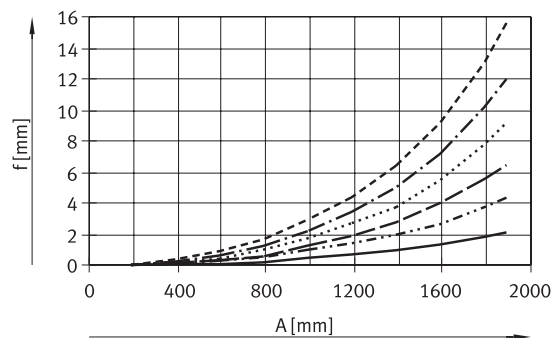
Interface for drive head [1], vertical



Size 90



- $m = 0 \text{ kg}$
- $m = 10 \text{ kg}$
- $m = 20 \text{ kg}$
- · - · - $m = 30 \text{ kg}$
- · — · — $m = 40 \text{ kg}$
- - - - $m = 50 \text{ kg}$

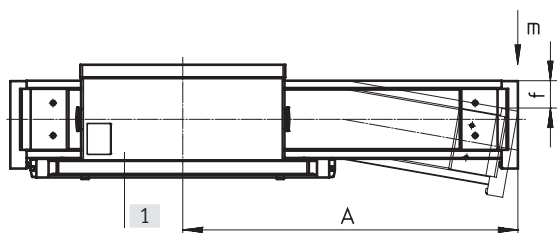


- $m = 0 \text{ kg}$
- $m = 10 \text{ kg}$
- $m = 20 \text{ kg}$
- · - · - $m = 30 \text{ kg}$
- · — · — $m = 40 \text{ kg}$
- - - - $m = 50 \text{ kg}$

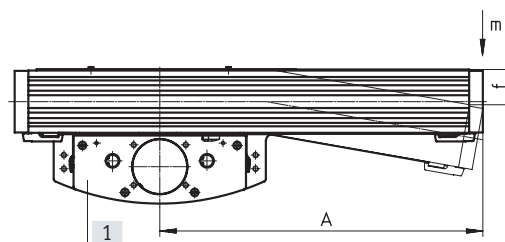
Datasheet

Deflection f as a function of the cantilever extension A and the payload m

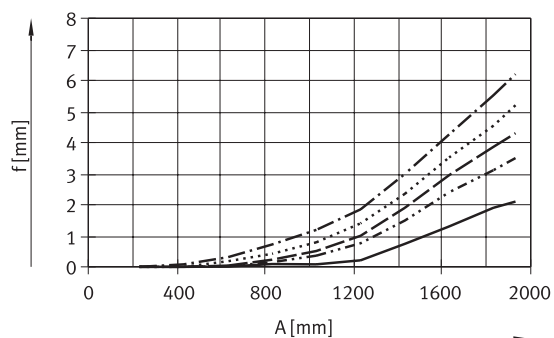
Interface for drive head [1], horizontal



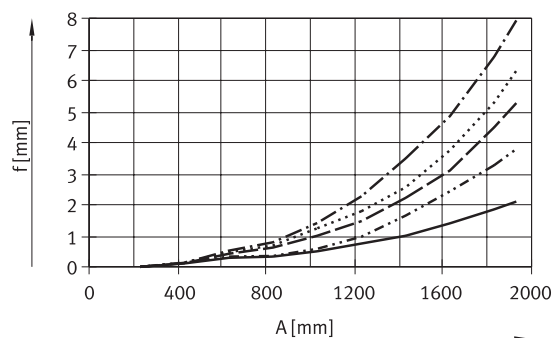
Interface for drive head [1], vertical



Size 110



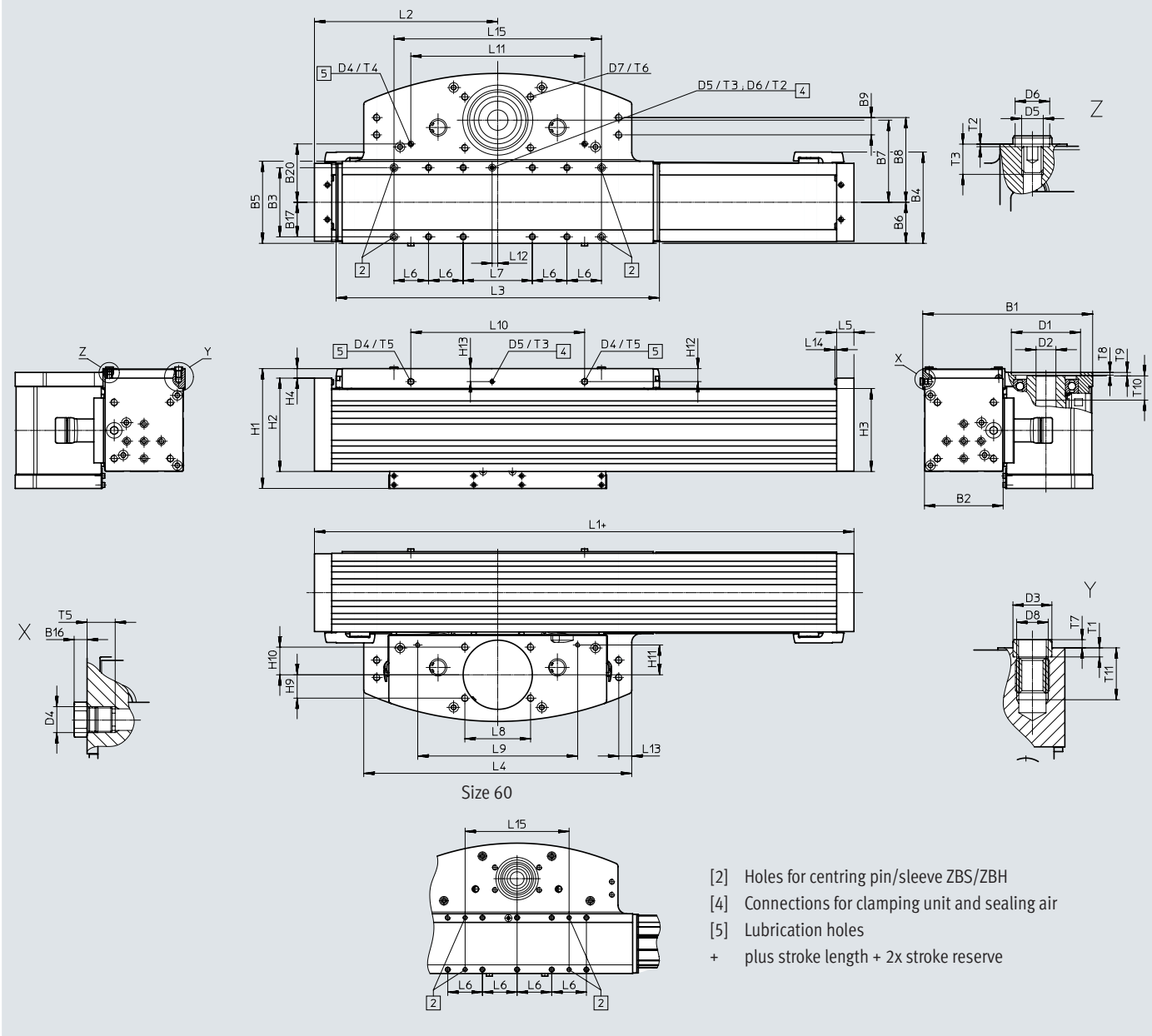
- $m = 0 \text{ kg}$
- $m = 20 \text{ kg}$
- $m = 30 \text{ kg}$
- · - · - $m = 40 \text{ kg}$
- · — · — $m = 50 \text{ kg}$



- $m = 0 \text{ kg}$
- $m = 20 \text{ kg}$
- $m = 30 \text{ kg}$
- · - · - $m = 40 \text{ kg}$
- · — · — $m = 50 \text{ kg}$

Datasheet

Dimensions

Download CAD data → www.festo.com


Size	B1	B2	B3	B4	B5	B6	B7	B8	B9	B16	B17
60	150.5	59.5	60	77.1	69	34.5	75	71.5	15	3	29.5
70	167.5	73	78	94.1	90	45	81.5	81.5	16	3	39
90	196.5	91	80	105.6	95	47.5	95	98	20	3	40
110	247.5	113	100	130.3	117	58.5	120	112	20	3	50

Size	B20	D1 ø H7	D2 ø H7	D3 ø H7	D4	D5	D6 ø H7	D7	D8	H1	H2
60	–	48	16	5	M6	M5	8	M6	M5	78.6	58
70	53	48	16	9	M6	M5	8	M6	M5	112	86
90	67.5	80	23	9	M6	M5	8	M8	M6	138.6	108
110	66	95	32	12	M6	M5	8	M8	M8	170.6	136.5

Datasheet

Size	H3	H4	H9	H10	H11	H12	H13	L1	L2 min.	L3	L4
60	47	9	13	13	29	14.3	13	330	165	280	233
70	73	11	13	13	29	16	16	406	203	356	253
90	95	11	27	32	34.5	15	15	424	212	374	310
110	120	14.5	40	40	48.5	22	22	508	254	458	358

Size	L5	L6	L7	L8	L9	L10	L11	L12	L13	L14	L15
60	20	40	–	51	120	64	–	10	7	2	120
70	20	40	70	51	120	187	187	5.5	12	2	230
90	20	40	80	76	185	201	201	6.5	15	2	240
110	20	40	120	80	210	248	248	14.2	15	2	280

Size	T1	T2	T3	T4	T5	T6	T7	T8	T9	T10	T11
60	2.5	0.6	7	–	6.5	12	2.5	2.1	4	26	10
70	2.1	0.6	7	6.1	6.5	12	1.9	2.1	4	26	10
90	2.1	0.6	7	6.5	6.5	16	1.9	3.1	4	28	12
110	2.6	0.6	7	6.5	6.5	17	2.4	2.8	4	33	16.2

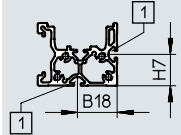
Datasheet

Dimensions

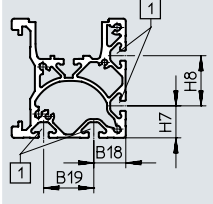
Download CAD data → www.festo.com

Profile

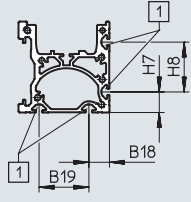
Size: 60



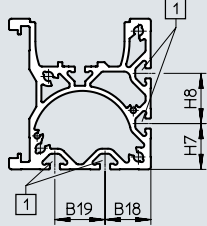
Size: 90



Size 70



Size 110



[1] Mounting slot for slot nut

Size	H7	H8	B18	B19
60	23.5	—	29.75	—
70	16.5	40	16.5	40
90	25.5	40	25.5	40
110	36.5	40	36.5	40

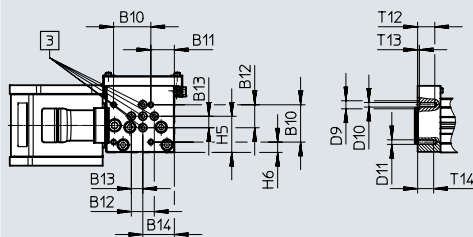
Datasheet

Dimensions

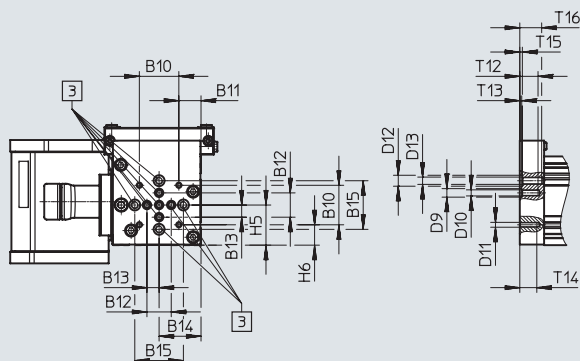
Download CAD data → www.festo.com

Interface on the front end for mounting the payload

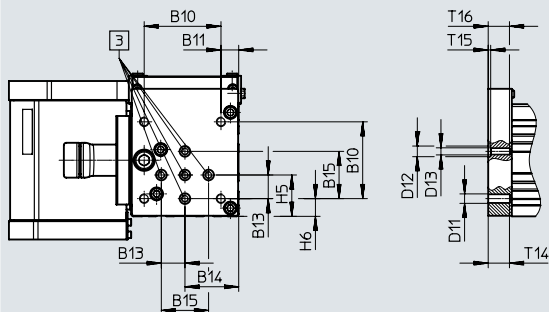
Size 60



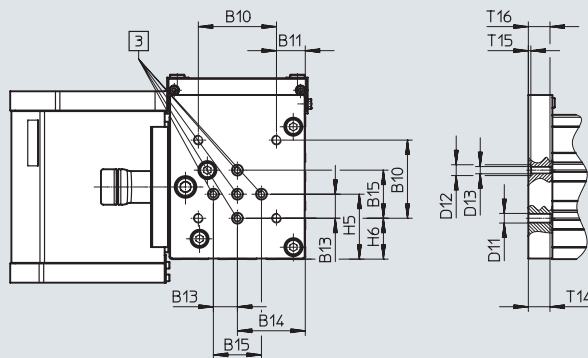
Size 70



Size: 90



Size 110



[3] Mounting slot for slot nut

Size	B10	B11	B12	B13	B14	B15	D9 ø H7	D10	D11
60	32.5	20.5	20	10	27.5	–	7	M4	M4
70	32.5	18.3	20	10	34.5	40	7	M5	M4
90	65	15	–	20	45.5	40	–	–	M8
110	65	24	–	20	56.5	40	–	–	M8

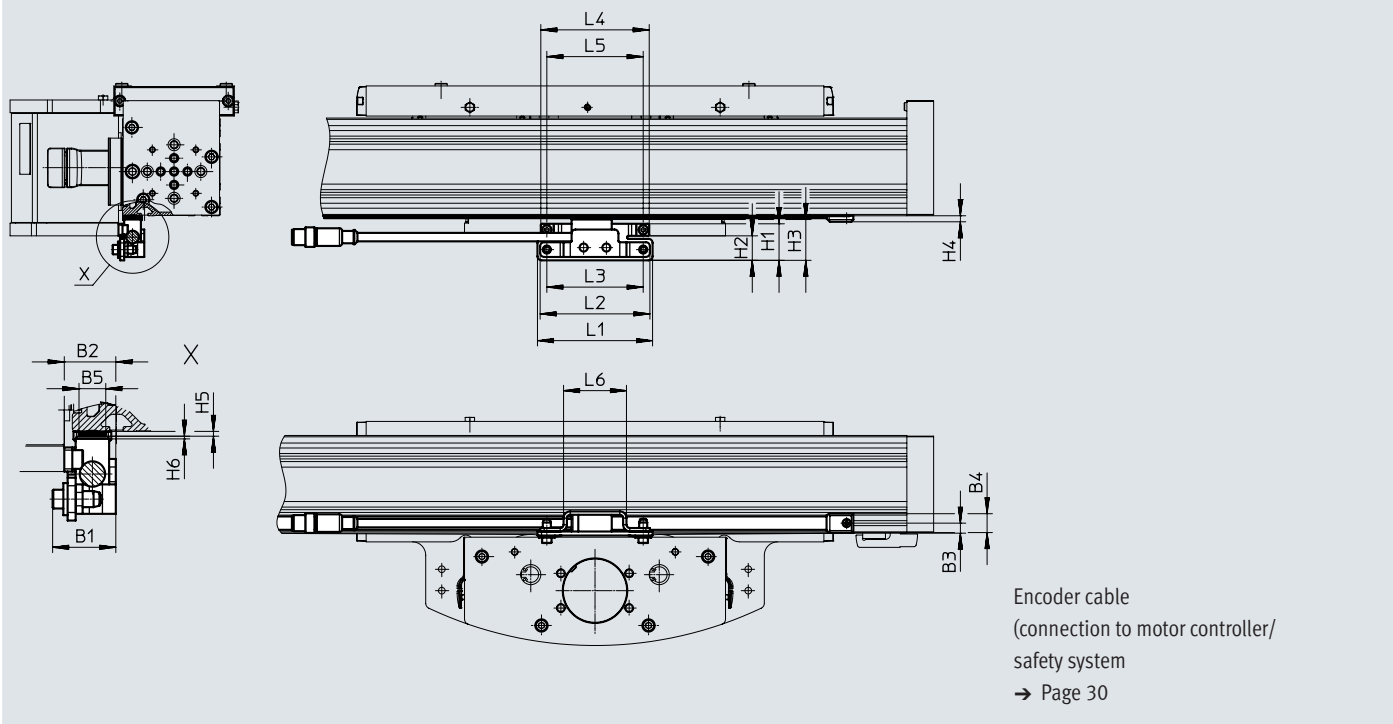
Size	D12 ø H7	D13	H5	H6	T12	T13	T14	T15	T16
60	–	–	31.5	9	15	1.6	14	–	–
70	9	M6	33	16.75	15	1.6	14	2.1	18
90	9	M6	35	15	–	–	18	2.1	18
110	9	M6	54	34	–	–	18	2.1	18

Datasheet

Dimensions

Download CAD data → www.festo.com

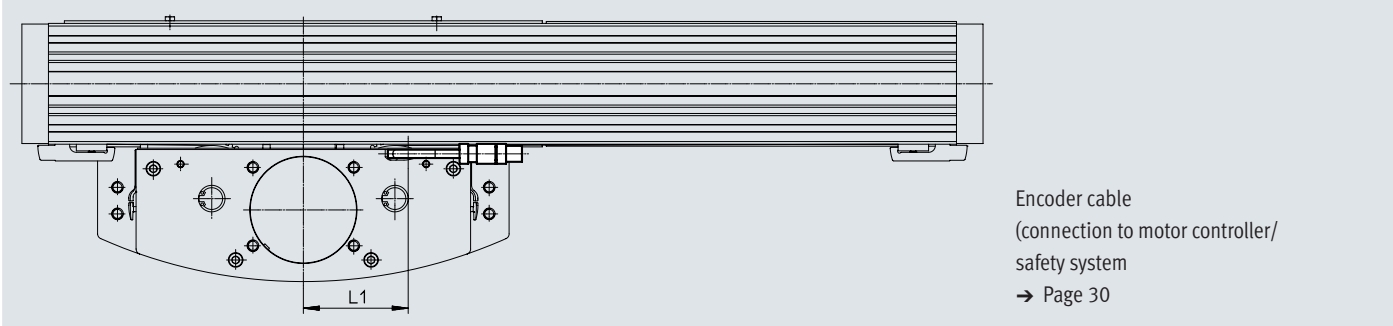
ELCC-TB-KF-6 0/70-...-M1 – with incremental displacement encoder



Size	B1	B2	B3	B4	B5	H1	H2	H3
60	32.6	26.8	15	14.1	10	30.5	19.1	30.5
70	23.6	19.3	7.5	14.1	10	27.3	18.3	30.5

Size	H4	H5	H6	L1	L2	L3	L4	L5	L6
60	4.5	1.8	1	86	82	72	81	72	47
70	4.5	1.8	1	86	82	72	81	72	47

ELCC-TB-KF-9 0/110-...-M1 – with incremental displacement encoder



Size	L1
90	79
110	79

Datasheet

Ordering data – Standard design

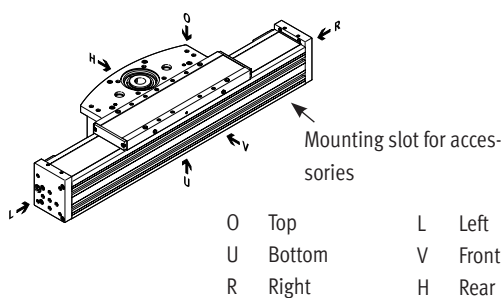
Key features:

- Stroke reserve: 0 mm
- Without cover strip
- Toothed belt material: Chloroprene rubber

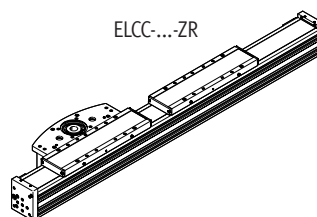
Size	Stroke [mm]	Part no.	Type
60	200	8082386	ELCC-TB-KF-60-200-0H-P0-CR
	300	8082387	ELCC-TB-KF-60-300-0H-P0-CR
	500	8082388	ELCC-TB-KF-60-500-0H-P0-CR
	600	8082389	ELCC-TB-KF-60-600-0H-P0-CR
	800	8082390	ELCC-TB-KF-60-800-0H-P0-CR
	1000	8082391	ELCC-TB-KF-60-1000-0H-P0-CR
70	200	8082392	ELCC-TB-KF-70-200-0H-P0-CR
	300	8082393	ELCC-TB-KF-70-300-0H-P0-CR
	500	8082394	ELCC-TB-KF-70-500-0H-P0-CR
	600	8082395	ELCC-TB-KF-70-600-0H-P0-CR
	800	8082396	ELCC-TB-KF-70-800-0H-P0-CR
	1000	8082397	ELCC-TB-KF-70-1000-0H-P0-CR
90	1200	8082398	ELCC-TB-KF-70-1200-0H-P0-CR
	200	8082399	ELCC-TB-KF-90-200-0H-P0-CR
	300	8082400	ELCC-TB-KF-90-300-0H-P0-CR
	500	8082401	ELCC-TB-KF-90-500-0H-P0-CR
	600	8082402	ELCC-TB-KF-90-600-0H-P0-CR
	800	8082403	ELCC-TB-KF-90-800-0H-P0-CR
	1000	8082404	ELCC-TB-KF-90-1000-0H-P0-CR
	1200	8082405	ELCC-TB-KF-90-1200-0H-P0-CR
	1500	8082406	ELCC-TB-KF-90-1500-0H-P0-CR
110	1700	8082407	ELCC-TB-KF-90-1700-0H-P0-CR
	2000	8082408	ELCC-TB-KF-90-2000-0H-P0-CR
	200	8082409	ELCC-TB-KF-110-200-0H-P0-CR
	300	8082410	ELCC-TB-KF-110-300-0H-P0-CR
	500	8082411	ELCC-TB-KF-110-500-0H-P0-CR
	600	8082412	ELCC-TB-KF-110-600-0H-P0-CR
	800	8082413	ELCC-TB-KF-110-800-0H-P0-CR
	1000	8082414	ELCC-TB-KF-110-1000-0H-P0-CR
	1200	8082415	ELCC-TB-KF-110-1200-0H-P0-CR
	1500	8082416	ELCC-TB-KF-110-1500-0H-P0-CR
	1700	8082417	ELCC-TB-KF-110-1700-0H-P0-CR
	2000	8082418	ELCC-TB-KF-110-2000-0H-P0-CR

Ordering data – Modular product system

Orientation guide



With additional slide



Ordering table		60	70	90	110	Conditions	Code	Enter code
Size		60	70	90	110			
Module no.		8060571	8060572	8060573	8060574			
Function		Cantilever axis					ELCC	ELCC
Drive system		Toothed belt					-TB	-TB
Guide		Recirculating ball bearing guide					-KF	-KF
Size		60	70	90	110		-...	
Stroke	Standard [mm]	200, 300, 500, 600, 800, 1000	200, 300, 500, 600, 800, 1000, 1200	200, 300, 500, 600, 800, 1000, 1200, 1500, 1700, 2000	200, 300, 500, 600, 800, 1000, 1200, 1500, 1700, 2000		-...	
	Variable [mm]	50 ... 1300	50 ... 1500	50 ... 2000	50 ... 2000		-...	
Stroke reserve	[mm]	0 ... 999 (0 = no stroke reserve)				[1]	-...H	
Additional slide		None						
		Slide on left				[2]	-ZL	
		Slide on right				[2]	-ZR	
		– Slide on left, with clamping unit				[2]	-ZLC	
		– Slide on right, with clamping unit				[2]	-ZRC	
Protection against particles		Without cover strip					-P0	
		With cover strip					-P9	
Additional features		None						
		Food-safe as per supplementary material information				[3]	-F1	
Toothed belt material		Chloroprene rubber					-CR	
		Uncoated PU for the food zone				–	-PU1	
		Coated PU				–	-PU2	
Displacement encoder, incremental		None						
		Resolution 2.5 µm					-M1	
Clamping unit		None						
		– Attached					-C	
Operating manual		With operating instructions						
		Without operating instructions					-DN	

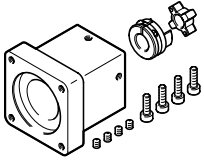
[1] ...H The sum of nominal stroke and 2x stroke reserve must not exceed the maximum stroke length

[2] ZL, ZR, ZLC, ZRC Reduction in working stroke in combination with additional slide → page 15

[3] F1 Select corresponding material for toothed belt in combination with feature F1

Accessories

Permitted axis/motor combinations for axial kits



Under the following links you will find all information about:

- Axis/motor combinations
- Permitted third-party motors
- Technical data
- Dimensions

For axial kits → Internet: [eamm-a](#)

Accessories

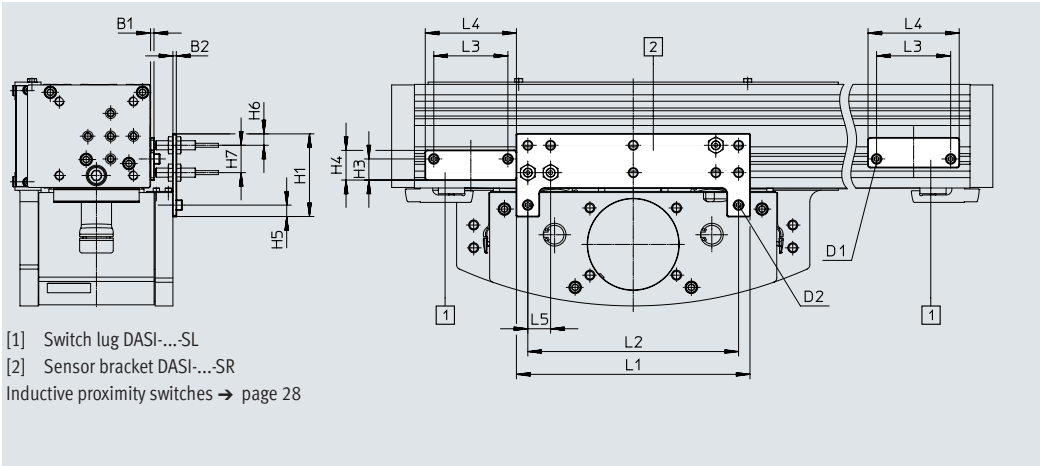
Switch lug DASI-E21-SL

For position sensing using a proximity switch SIEN-8MB

Material:
Galvanised steel
RoHS-compliant

Sensor bracket DASI-E21-SR

For proximity switch SIEN-8MB



Dimensions and ordering data								
For size	B1	B2	D1	D2	H1	H3	H4	H5
60	3	3	M4	M5	77.8	19	24	10
70	3	3	M4	M5	101.5	16	21	10
90	3	3	M5	M5	72.5	18.5	26	10
110	3	3	M5	M5	83.5	18.5	26	10

For size	H6	H7	L1	L2	L3	L4	L5
60	10	28	140	120	50	60	20
70	10	22	140	120	50	60	20
90	10	24	205	185	65	80	20
110	10	24	230	210	65	80	20

Switch lug					Sensor bracket				
For size	Weight [g]	Part no.	Type	PE ¹⁾	For size	Weight [g]	Part no.	Type	PE ¹⁾
60	40	8081324	DASI-E21-60-S8-SL	1	60	132	8081066	DASI-E21-60-S8-SR	1
70	36	8081063	DASI-E21-70-S8-SL		70	225	8081064	DASI-E21-70-S8-SR	
90	77	8081061	DASI-E21-9 0/110-S8-SL		90	247	8081060	DASI-E21-90-S8-SR	
110	77	8081061	DASI-E21-9 0/110-S8-SL		110	326	8081062	DASI-E21-110-S8-SR	

1) Packaging unit

Accessories

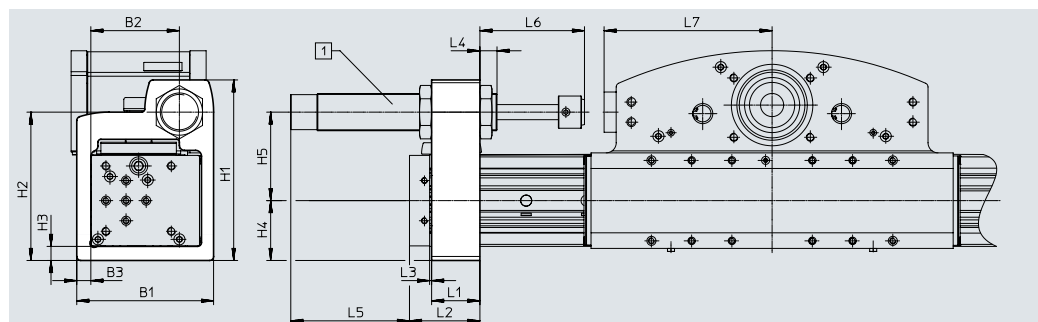
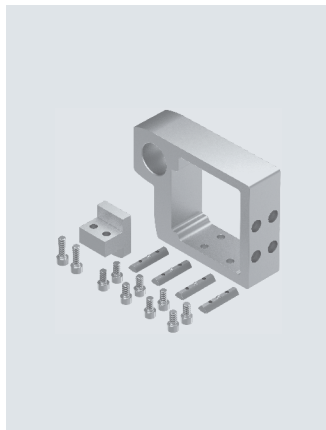
Shock absorber retainer DAYP-E21

Material:
Retainer, stop: Anodised wrought aluminium alloy
RoHS-compliant



Note

The additional length of the profile required for the installation space must be taken into account when ordering the axis (stroke specification).



[1] Shock absorber not included in the scope of delivery.
Ordering data → page 29

Dimensions and ordering data

For size	B1	B2	B3	H1	H2	H3	H4	H5	L1	L2 min.
60	78	46	10	120.5	101.5	10	37.5	64	28	50
70	106	70	10	143.5	118	10	44.5	73.5	32	54
90	136	88	14	179.5	147.5	14	59.5	88	48	70
110	178	113	20	218.5	178.5	20	76.5	102	48	70

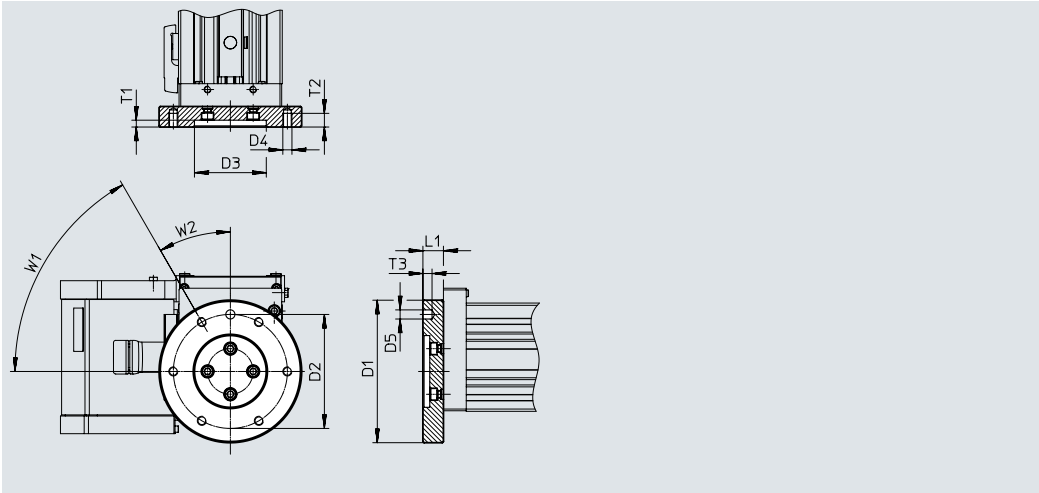
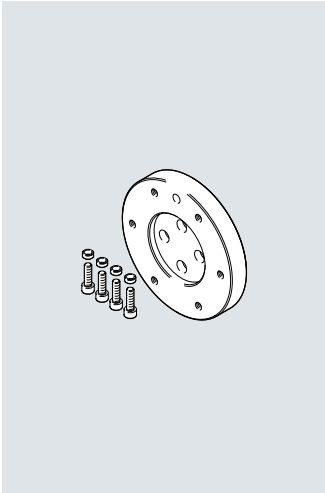
For size	L3 min.	L4 min.	L5	L6 min.	L7	Weight [g]	Part no.	Type	PE ¹⁾
60	2	13	41	58.5	126.5	356	8067058	DAYP-E21-60	1
70	2	23	75	84.5	138.5	586	8067060	DAYP-E21-70	
90	2	17	118	104	167	1552	8067062	DAYP-E21-90	
110	2	17	118	104	191	2323	8067064	DAYP-E21-110	

1) Packaging unit

Accessories

Adapter kit DHAA-R
For interface to ISO 9409-1:2004

Material:
Adapter plate: Wrought aluminium alloy
Screws: Galvanised steel
RoHS-compliant

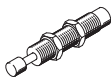


Dimensions and ordering data							
For size	D1 Ø h8	D2 Ø	D3 Ø H7	D4	D5 Ø H7	L1	T1
70	125	100	63	M8	8	18	6
90							
110							

For size	T2	T3	W1	W2	Weight [g]	Part no.	Type	PE ¹⁾
70	12	8	60°	30°	559	8082459	DHAA-R-E21-70...110RF1-100	1
90								
110								

1) Packaging unit

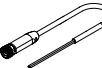
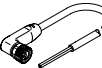
Accessories

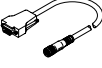
Ordering data					
	For size	Description	Part no.	Type	PE ¹⁾
Shock absorber YSR					
	60	For use in combination with shock absorber retainer DAYP-E21	34574	YSR-20-25-C	1
	70		160273	YSR-25-40-C	
	90, 110		160274	YSR-32-60-C	
Slot nut NST					
	60, 70	For profile slot	150914	NST-5-M5-1	1
			8047843	NST-5-M5-10	10
			8047878	NST-5-M5-50	50
	90, 110	For profile slot	150915	NST-8-M6-1	1
			8047868	NST-8-M6-10	10
			8047869	NST-8-M6-50	50
Centring pin ZBS/centring sleeve ZBH					
	60	For mounting the drive head	150928	ZBS-5	10
	70, 90		8137184	ZBH-9-B	
	110		8137185	ZBH-12-B	
	60, 70	For centring on the front end	8146544	ZBH-7-B	
	70, 90, 110		8137184	ZBH-9-B	
	Slot cover ABP				
	60, 70	• For mounting slot • Every 0.5 m	151681	ABP-5	2
	90, 110		151682	ABP-8	
Drive shaft adapter EAMB					
	60, 70	• Can be used as an alternative interface, as required • No drive shaft adapter is required for the axis/motor combinations → page 25	558036	EAMB-24-6-15X21-16X20	1
	90		558037	EAMB-34-6-25X26-23X27	
	110		558038	EAMB-44-7-35X30-32X32	
Clamping component EADT					
	60	Tool for retensioning the cover strip	8058451	EADT-S-L5-70	1
	70, 90		8097157	EADT-S-L5-90	
	110		8058450	EADT-S-L5-120	
Connecting shaft KSK					
	60, 70	• For torsion-resistant transmission of torques • For slip-free transmission of feed rates • To operate two cantilever axes in parallel using one motor	562521	KSK-80-	1
	90		562522	KSK-120-	
	110		562523	KSK-185-	

1) Packaging unit

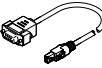
Accessories

Ordering data – Proximity switch M8 (round design), inductive						Datasheets → Internet: sien	
	Electrical connection	LED	Switching output	Cable length [m]	Part no.	Type	
N/O							
	Cable, 3-core	■	PNP	2.5	150386	SIEN-M8B-PS-K-L	
			NPN	2.5	150384	SIEN-M8B-NS-K-L	
	Plug M8x1, 3-pin	■	PNP	–	150387	SIEN-M8B-PS-S-L	
			NPN	–	150385	SIEN-M8B-NS-S-L	
N/C							
	Cable, 3-core	■	PNP	2.5	150390	SIEN-M8B-PO-K-L	
			NPN	2.5	150388	SIEN-M8B-NO-K-L	
	Plug M8x1, 3-pin	■	PNP	–	150391	SIEN-M8B-PO-S-L	
			NPN	–	150389	SIEN-M8B-NO-S-L	

Ordering data – Connecting cables							Datasheets → Internet: neba
	Electrical connection 1, connection technology	Electrical connection 1, cable outlet	Electrical connection 2, connection technology	Electrical connection 2, number of pins/cores	Cable length [m]	Part no.	Type
	M8x1 A-coded to EN 61076-2-104	Straight	Open end	3	2.5	8078223	NEBA-M8G3-U-2.5-N-LE3
					5.0	8078224	NEBA-M8G3-U-5-N-LE3
	M8x1 A-coded to EN 61076-2-104	Angled	Open end	3	2.5	8078230	NEBA-M8W3-U-2.5-N-LE3
					5.0	8078231	NEBA-M8W3-U-5-N-LE3

Ordering data – Encoder cables for displacement encoder system, ELCC-...-M1							Data sheets → Internet: nebm
	Electrical connection, left	Electrical connection, right	Cable length [m]	Part no.	Type		
	Displacement encoder ELCC-...-M1	Motor controller CMMP-AS	5	1599105	NEBM-M12G8-E-5-S1G9-V3		
			10	1599106	NEBM-M12G8-E-10-S1G9-V3		
			15	1599107	NEBM-M12G8-E-15-S1G9-V3		
			X ¹⁾	1599108	NEBM-M12G8-E-...-S1G9-V3		

1) Max. cable length: 25 m.

Ordering data – Adapter			
	Description	Part no.	Type
	Required in combination with the servo drive CMMT-AS as adapter between encoder cable NEBM-M12G8-...-V3 and interface X3 (position encoder 2)	8106112	NEFM-S1G9-K-0.5-R3G8