

Modular and scalable automation concept for connector assembly

Key modules: Servo press kit and compact handling systems



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Highlights

- Modular and scalable automation concept
- Easy commissioning and maintenance: Solution is based on modules using as many standard parts as possible: Compact handling system YXMx, servo press kit YJKP, controller CECC-X in combination with valve terminal CPX/MPA, common base plate
- Easy engineering and commissioning: System kits YXMx and YJKP comprising kinematics, controller and application software
- No programming skills requires
 - Graphic user interface (sequencer) for simple and reliable generation of program sequences in CODESYS
 - Festo Handling Motion Lib with predefined function elements

Customer

Harwin PLC Europe, located in Portsmouth, Great Britain, is a manufacturer of electronic connectors and mechanical components for PCBs.

Project

Highly automated assembly line for electronic connectors, capable of producing hundreds of thousand of connectors of the Gecko series a year with a wide range of connector configurations ranging from 4 to 50 pins per connector. The assembly line consists of three main stations:

- (1) Inserting the pin contacts into the connector housings,
- (2) Press-fitting the pins and
- (3) bending the pins

Requirements

- Increase efficiency of manufacturing process
- High level of automation and high degree of flexibility were needed to be able to produce differently shaped and sized connectors on the same assembly line
- Precision, repetition accuracy, flexibility and reliability
- Modular concept to future-proof Harwin's assembly lines

Solution

- Built around the servo press kit YJKP and the compact handling system YXMx
- The handling systems YXMx takes care of the X/Y movements of the workpiece carries and the plastic housings assembled in the system stations.
- The servo press kit YJKP provides easy-to-configure position and force-controlled movement in the Z plane and is used for press-fitting and bending the contact pins.
- The Festo solutions enable maximum standardisation and modularisation, as standard parts are used everywhere.

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Customer Harwin is convinced by the Festo solution

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Festo solution

„The Festo solution give us the accuracy, flexibility and reliability we need to produce high-end connectors for the electronics industry and reduces our engineering efforts significantly.”

Paul McGuinness

Operations Director at Harwin

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Assembly line for Gecko connectors consists of three key stations

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1 Inserting the pin contacts into the connector housings (pin shooter):

The workpiece carriers are equipped with the required connector housings and are positioned by using the compact handling system YXMx so the contact pins can be inserted.

2 Press-fitting the pins:

The servo press presses the contact pins into the connector housing. The precision gripper HGPT from Festo locates the workpiece carriers holding the connector housings while the pins are fitted.

3 Press-fitting the pins:

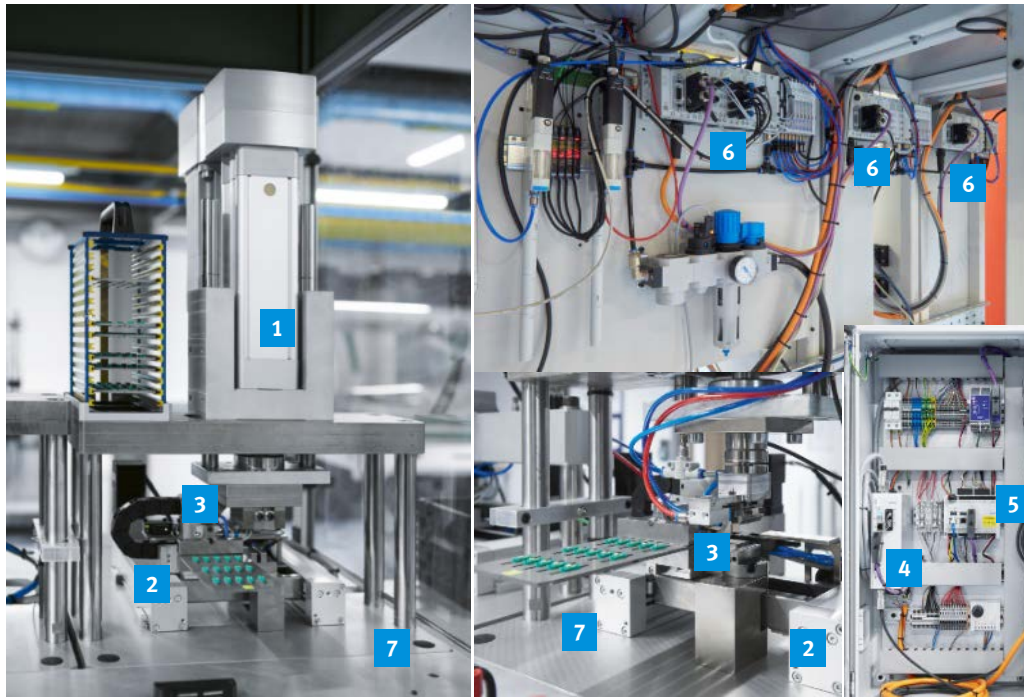
The servo press presses the contact pins into the connector housing. The precision gripper HGPT from Festo locates the workpiece carriers holding the connector housings while the pins are fitted.

1 ... 3 In all stations, the electric and pneumatic drivers are controlled by their own controller CECC-X together with a valve terminal CPX/MPA

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Festo solution – Standard modules, common parts

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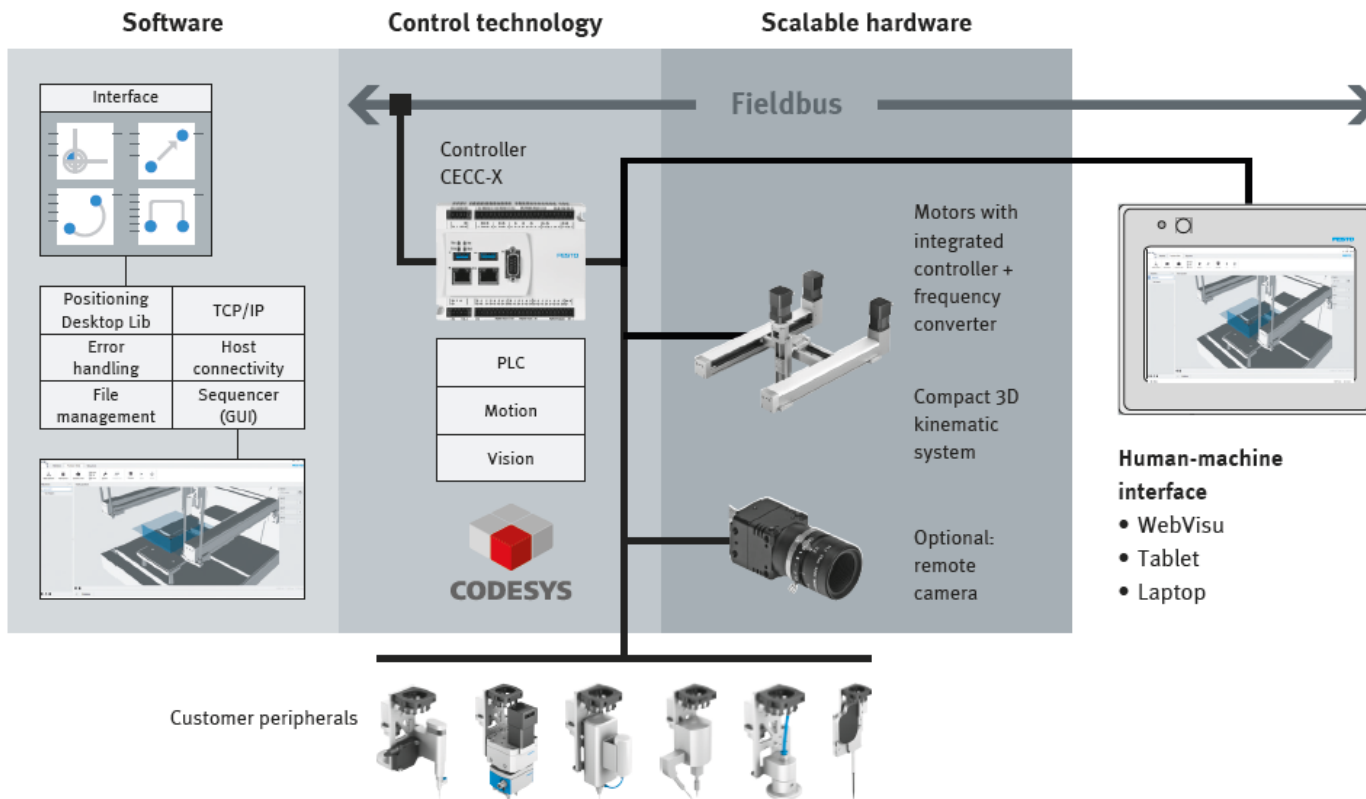
All stations are based on modules using as many standard parts as possible:

- 1 Servo Press Kit YJKP
- 2 Compact Handling System YXMx
- 3 Precision gripper HGPT
- 4 Motorcontroller CMMP-AS
- 5 Controller CECC-X (PLC)
- 6 Valve Terminal CPX/MPA
- 7 Common base plate

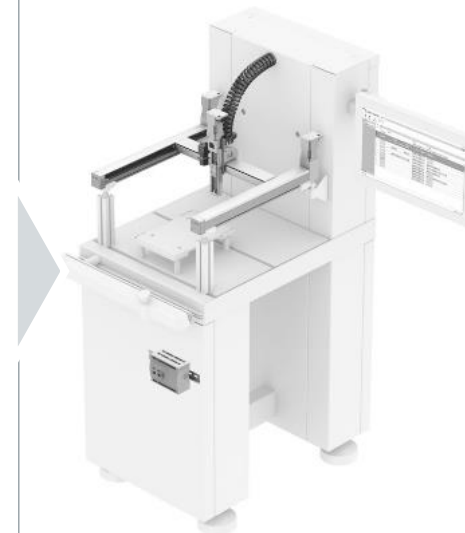
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Compact handling system – System structure

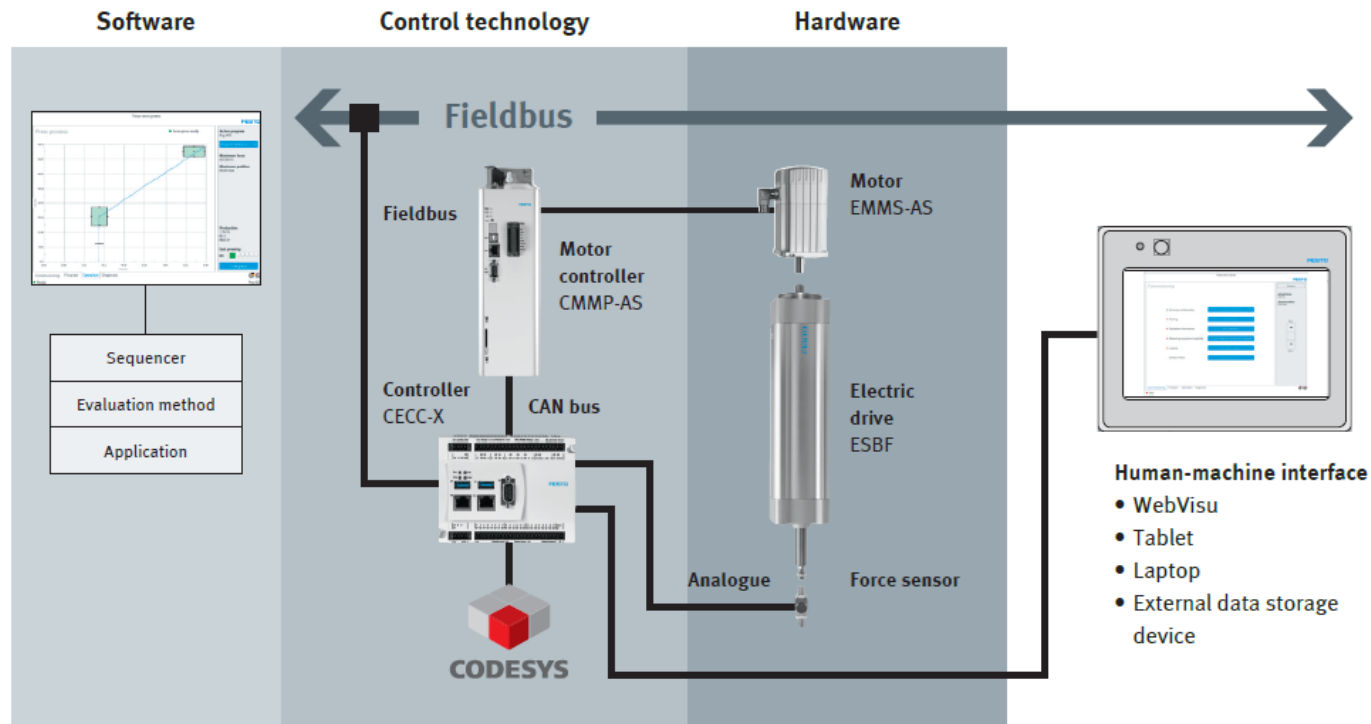


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Compact handling system – System structure



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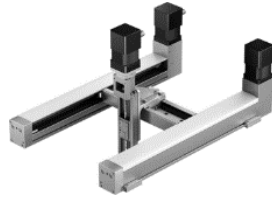
Handling solution for moving and positioning a dispensing head

Solution components in detail



Valve terminals CPX/MPA

- Proportional technology
- Integrated, convenient diagnostics thanks to serial linking
- Up to 8 voltage zones
- Controlled via fieldbus or control block
- Max. 64 valve positions / max. 128 solenoid coils
- Digital inputs/outputs, Analogue inputs/outputs
- Parameterisation of inputs and outputs
- Integrated convenient diagnostic system
- Preventive maintenance concepts



Compact planar surface gantry EXCM-30

- Rated load for maximum dynamic response: 3kg
- Stroke length X-axis: 100 ... 700 mm
- Stroke length Y-axis: 110, 160, 210, 260, 360
- Maximum acceleration: 10 m/s²
- Maximum speed: 0.5 m/s
- Stepper motors with integrated controller and frequency converter



Electric cylinder ESBF and Servo motor EMMS-AS

- Feed forces of up to 17 kN
- Size 32, 40, 50, 63, 80, 100
- Stroke length 30 ... 1500 mm
- Force 600 ... 1700 N
- Motor can be mounted using axial or parallel kit
- Linear drive with ball screw in Clean Design
- Including guide unit EAGF
- For protecting electric cylinders ESBF and EPCO against torsion at high torque loads
- Recirculating ball bearing guide



Parallel grippers HGPT

- Size 16,20, 25, 35,40, 50, 63, 80
- Gripping Force (Standard) 106 ... 3120 N
- Gripping Force (Heavy-Duty) 192 ... 6300N
- Repetition Accuracy: ±0,01 ... ±0,025



Controller CECC-X

- Large number of functions in a very compact space
- High performance (dual-core processor)
- Interface variety
- Programming based on CODESYS V3
- Future-safe for Industry 4.0 thanks to OPC UA interface

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