

# Radial gripper DHRS-10-A

Part number: 1310159

FESTO



 General operating condition

## Data sheet

Feature	Value
Size	10
Max. interchangeability	≤0.2 mm
Max. opening angle	180 deg
Rotational symmetry	≤0.2 mm
Pneumatic gripper repetition accuracy	≤0.1 mm
Number of gripper jaws	2
Mounting position	Any
Mode of operation	Double-acting
Gripper function	Radial
Structural design	Positively driven motion sequence
Position sensing	For Hall sensor
Symbol	00991894
Operating pressure	2 bar ... 8 bar
Max. operating frequency of pneumatic gripper	≤4 Hz
Min. opening time at 6 bar	35 ms
Min. closing time at 6 bar	91 ms
Operating medium	Compressed air as per ISO 8573-1:2010 [7:4:4]
Information on operating and pilot media	Operation with oil lubrication possible (required for further use)
Corrosion resistance class (CRC)	1 - Low corrosion stress
LABS (PWIS) conformity	VDMA24364-B2-L
Suitability for the production of Li-ion batteries	Metals with more than 5% by mass of copper are excluded from use. This excludes printed circuit boards, cables, electrical connectors and coils.
Ambient temperature	5 °C ... 60 °C
Total gripping torque at 0.6 MPa (6 bar, 87 psi), opening	21 Ncm
Total gripping torque at 6 bar, closing	15 Ncm
Mass moment of inertia	0.03 kgcm <sup>2</sup>
Maximum force on gripper jaw F <sub>z</sub> , static	30 N
Maximum torque on gripper jaw, M <sub>x</sub> static	0.8 Nm
Maximum torque on gripper jaw, M <sub>y</sub> static	0.8 Nm
Maximum torque on gripper jaw, M <sub>z</sub> static	0.8 Nm
Product weight	44 g
Type of mounting	Alternatively: With internal thread and centering sleeve Via through-hole and centering sleeve
Pneumatic connection	M3
Note on materials	RoHS compliant

<b>Feature</b>	<b>Value</b>
Cover cap material	PA
Housing material	Wrought aluminum alloy, hard-anodized
Gripper jaw material	High-alloy steel