

# Electric cylinder ESBF-LS-40-400-3P

Part number: 8022588

FESTO



 General operating condition

## Data sheet

Feature	Value
Working stroke	400 mm
Size	40
Stroke	400 mm
Piston rod thread	M12x1.25
Reversing backlash	100 µm
Screw diameter	16 mm
Spindle pitch	3 mm/U
Max. angle of rotation of the piston rod +/-	0.2 deg
Based on norm	ISO 15552
Mounting position	Any
Piston rod end	External thread
Motor type	Stepper motor Servo motor
Position sensing	For proximity sensor
Structural design	Electric cylinder with lead screw spindle
Spindle type	Lead screw
Symbol	00991941
Protection against torsion/guide	With plain-bearing guide
Max. acceleration	2.5 m/s <sup>2</sup>
Max. rotational speed	1000 rpm
Max. speed	0.15 m/s
Repetition accuracy	±0.05 mm
Duty cycle	100%
Corrosion resistance class (CRC)	2 - Moderate corrosion stress
LABS (PWIS) conformity	VDMA24364 zone III
Storage temperature	-20 °C ... 60 °C
For use in the food industry	See supplementary material information
Relative air humidity	0 - 95 %
Degree of protection	IP40
Ambient temperature	0 °C ... 50 °C
Max. driving torque	2.4 Nm
Max. radial force on actuator shaft	130 N
Max. feed force Fx	1000 N
No-load driving torque	0.2 Nm
Guide value for payload, horizontal	100 kg
Guide value for payload, vertical	100 kg

Feature	Value
Mass moment of inertia JH per meter of stroke	1.0187 kgcm <sup>2</sup>
Mass moment of inertia JL per kg of payload	0.0063 kgcm <sup>2</sup>
Mass moment of inertia JO	0.0449 kgcm <sup>2</sup>
Moving mass at 0 mm stroke	317 g
Additional moving mass per 10 mm stroke	11 g
Basic weight with 0 mm stroke	1079 g
Additional weight per 10 mm stroke	48 g
Type of mounting	With internal thread or accessory
Interface code, actuator	D40
Note on materials	RoHS-compliant
Cover material	Wrought aluminum alloy, smooth-anodized
Piston rod material	High-alloy stainless steel
Material of screws	Steel, galvanized
Ball screw nut material	Roller bearing steel
Spindle material	Roller bearing steel
Material of cylinder barrel	Wrought aluminum alloy, smooth-anodized