

Radial gripper DHRC-10-A

Part number: 8125472

FESTO



[PDF](#) General operating condition

Data sheet

Feature	Value
Size	10
Max. replacement accuracy	≤0.2 mm
Max. opening angle	180 deg
Rotationally symmetrical	≤0.2 mm
Repetition accuracy, gripper	≤0.1 mm
Number of gripper jaws	2
Drive system	Pneumatic
Mounting position	optional
Mode of operation	Double-acting
Gripper function	Radial
Gripper force back-up	None
Design	Connection direction at side Force pilot operated motion sequence
Position detection	Via proximity switch
Symbol	00991894
Operating pressure	0.1 MPa ... 0.8 MPa
Operating pressure	1 bar ... 8 bar
Operating pressure	14.5 psi ... 116 psi
Max. operating frequency of gripper	≤3 Hz
Min. opening time at 0.6 MPa (6 bar, 87 psi)	28 ms
Min. closing time at 0.6 MPa (6 bar, 87 psi)	43 ms
Operating medium	Compressed air to ISO 8573-1:2010 [7:4:4]
Note on operating and pilot medium	Lubricated operation possible (in which case lubricated operation will always be required)
Corrosion resistance class CRC	0 - No corrosion stress
LABS (PWIS) conformity	VDMA24364-B2-L
Suitability for the production of Li-ion batteries	Suitable for battery production with reduced Cu/Zn/Ni values (F1a)
Ambient temperature	-10 °C ... 60 °C
Total gripping torque at 0.6 MPa (6 bar, 87 psi), opening	25.3 Ncm
Total gripper torque, closing, 0.6 MPa (6 bar, 87 psi)	20.4 Ncm
Mass moment of inertia	0.04 kgcm ²
Max. force on gripper jaw Fz static	35 N
Max. torque at gripper Mx static	0.5 Nm
Max. torque at gripper My static	0.5 Nm
Max. torque at gripper Mz static	0.5 Nm

Feature	Value
Product weight	54 g
Type of mounting	Either: Direct mounting via through-hole Direct mounting via thread Via through-hole and dowel pin Via female thread and dowel pin
Pneumatic connection	M3
Note on materials	RoHS-compliant
Material cover cap	Wrought aluminium alloy, anodised
Material housing	Anodised wrought aluminium alloy
Material gripper jaws	High-alloy steel