

Servo motor EMMT-AS-190-L-HT-R3MYB

Part number: 8148395

FESTO



 General operating condition

Data sheet

| Feature | Value |
|---|--|
| Ambient temperature | -15 °C ... 40 °C |
| Note on ambient temperature | Up to 80°C with derating of -1.5% per degree Celsius |
| Max. installation height | 4000 m |
| Note on max. installation height | As of 1,000 m: only with derating of -1.0% per 100 m |
| Storage temperature | -20 °C ... 70 °C |
| Relative air humidity | 0 - 90% |
| Conforms to standard | IEC 60034 |
| Temperature class as per EN 60034-1 | F |
| Max. winding temperature | 155 °C |
| Rating class as per EN 60034-1 | S1 |
| Temperature monitoring | Digital motor temperature transmission via EnDat® 2.2 |
| Motor type to EN 60034-7 | IM V1 IM V3 |
| Mounting position | Any |
| Degree of protection | IP21 |
| Note on degree of protection | IP67 for motor housing including connection components |
| Concentricity, coaxiality, axial runout to DIN SPEC 42955 | N |
| Balance quality | G 2.5 |
| Detent torque | <1.0% of peak torque |
| Bearing lifetime under nominal conditions | 20000 h |
| Interface code, motor out | 190B |
| Electrical connection 1, connection type | Hybrid plug |
| Electrical connection 1, connector system | M40x1 |
| Electrical connection 1, number of connections/cores | 15 |
| Electrical connection 1, connection pattern | 00997380 |
| Pollution degree | 2 |
| Note on materials | RoHS compliant |
| Corrosion resistance class CRC | 0 - No corrosion stress |
| LABS (PWIS) conformity | VDMA24364 zone III |
| Vibration resistance | As per EN 60068-2-6 |
| Shock resistance | As per EN 60068-2-29 15 g/11 ms to EN 60068-2-27 |
| Approval | c UL us - Recognised (Oil) |
| CE mark (see declaration of conformity) | To EU EMC Directive To EU Low Voltage Directive In accordance with EU RoHS Directive |

| Feature | Value |
|---|---|
| UKCA marking (see declaration of conformity) | To UK RoHS instructions To UK regulations for electrical equipment |
| Certificate issuing authority | TÜV 968/FSP 2317.01/25 UL E342973 |
| Nominal operating voltage DC | 680 V |
| Type of winding switch | Star inside |
| Number of pole pairs | 5 |
| Standstill torque | 93.7 Nm |
| Nominal torque | 82.4 Nm |
| Peak torque | 183.3 Nm |
| Nominal rotary speed | 1000 rpm |
| Max. rotational speed | 1654 rpm |
| Max. mechanical speed | 8000 rpm |
| Angular acceleration | $\leq 100000 \text{ rad/s}^2$ |
| Nominal power rating of motor | 8629 W |
| Continuous stall current | 22.8 A |
| Nominal motor current | 20 A |
| Peak current | 49.7 A |
| Motor constant | 4.12 Nm/A |
| Standstill torque constant | 4.79 Nm/A |
| Voltage constant, phase-to-phase | 289.7 mVmin |
| Phase-phase winding resistance | 0.358 Ohm |
| Phase-phase winding inductance | 13.8 mH |
| Winding longitudinal inductivity Ld (phase) | 6.95 mH |
| Winding cross inductivity Lq (phase) | 6.9 mH |
| Electric time constant | 38.8 ms |
| Thermal time constant | 80 min |
| Thermal resistance | 0.3 K/W |
| Measuring flange | 450 x 450 x 30 mm, steel |
| Total mass moment of inertia of output | 195 kgcm ² |
| Product weight | 61500 g |
| Permissible axial shaft load | 520 N |
| Permissible radial shaft load | 2620 N |
| Rotor position sensor | Absolute multi-turn safety encoder |
| rotor position sensor, manufacturer designation | EQI 1331 |
| rotor position sensor, absolute detectable revolutions | 4096 |
| Rotor position encoder interface | EnDat 22 |
| Rotor position sensor, encoder measuring principle | Inductive |
| rotor position sensor, DC operating voltage | 5 V |
| rotor position sensor, DC operating voltage range | 3.6 V ... 14 V |
| rotor position sensor, position values per revolution | 524288 |
| Rotor position transducer resolution | 19 bit |
| rotor position sensor, system accuracy of angle measurement | -65 arcsec ... 65 arcsec |
| Brake holding torque | 115 Nm |
| Operating voltage DC for brake | 24 V |
| Brake current consumption | 2.08 A |
| Power consumption, brake | 50 W |
| Brake separation time | 190 ms |
| Brake closing time | 65 ms |
| DC brake response delay | 12 ms |
| Max. brake no-load speed | 8000 rpm |
| Max. friction per braking process | 62000 J |
| Number of emergency stops per hour | 1 |

| Feature | Value |
|---|---|
| Total brake friction | 13000 kJ |
| Mass moment of inertia of brake | 50 kgcm ² |
| Switching cycles holding brake | 5 million idle actuations (without friction work!) |
| Safety device | Safety device |
| Maximum SIL | Safety integrity level 3 See user documentation |
| Safety sub-functions up to SIL2 | Reliable recording and transmission of single-turn position data |
| Safety sub-functions up to SIL3 | Reliable recording and transmission of single-turn position data, only with additional software function in the servo drive |
| Maximum PL and category | Performance Level e, category 3 See user documentation |
| Safety sub-function up to PL d, Cat. 3 | Reliable recording and transmission of single-turn position data |
| Safety sub-function up to PL e, Cat. 3 | Reliable recording and transmission of single-turn position data, only with additional software function in the servo drive |
| PFHd, subcomponent | 15 x 10E-9, encoder |
| Duration of use Tm, subcomponent | 20 years, rotor position encoder |
| Mean time to failure (MTTF), subcomponent | 190 years, rotor position encoder |
| Energy efficiency | ENEFF (CN) / Class 1 |