

Servo motor EMMT-AS-80-S-HS-RSB

Part number: 5255431

FESTO



 General operating condition

Data sheet

Feature	Value
Ambient temperature	-40 °C ... 40 °C
Note on ambient temperature	Up to 80 °C with derating of -1.5% per degree Celsius
Max. installation height	4000 m
Information on max. installation height	with 1,000 m and longer only with derating of -1.0% per 100 m
Storage temperature	-40 °C ... 70 °C
Relative air humidity	0 - 90%
Conforms to standard	IEC 60034
Thermal class according to EN 60034-1	F
Max. winding temperature	155 °C
Rating class according to EN 60034-1	S1
Temperature monitoring	Digital motor temperature transmission via EnDat® 2.2
Motor type as per EN 60034-7	IM V1 IM V3
Mounting position	Any
Degree of protection	IP40
Note on degree of protection	IP67 for motor housing, incl. connection technology
Concentricity, coaxiality, axial runout according to DIN SPEC 42955	N
Balancing quality	G 2.5
Detent torque	<1.0% of peak torque
Bearing lifetime, under nominal conditions	20000 h
Interface code, motor out	80P
Electrical connection 1, connection type	Hybrid plug
Electrical connection 1, connection technology	M23x1
Electrical connection 1, number of pins/wires	15
Electrical connection for input 1, connection pattern	00995913
Contamination level	2
Note on materials	RoHS compliant
Corrosion resistance class (CRC)	0 - No corrosion stress
LABS (PWIS) conformity	VDMA24364 Zone III
Vibration resistance	Transport application test with severity level 2 as per FN 942017-4 and EN 60068-2-6
Shock resistance	Shock test with severity level 2 as per FN 942017-5 and EN 60068-2-27
Certification	RCM compliance mark c UL us - recognized (OL)
CE marking (see declaration of conformity)	As per EU EMC directive As per EU low voltage directive As per EU RoHS directive

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UKCA marking (see declaration of conformity)	To UK RoHS instructions To UK instructions for electrical equipment
Certificate issuing authority	UL E342973
Nominal operating voltage DC	680 V
Type of winding switch	Star inside
Number of pole pairs	5
Stall torque	1.46 Nm
Nominal torque	1.3 Nm
Peak torque	2.8 Nm
Nominal rotary speed	3000 rpm
Max. rotational speed	8950 rpm
Max. mechanical speed	14000 rpm
Angular acceleration	$\leq 100000 \text{ rad/s}^2$
Motor nominal power	408 W
Continuous stall current	2 A
Motor nominal current	1.76 A
Peak current	5.4 A
Motor constants	0.74 Nm/A
Standstill torque constant	0.89 Nm/A
Voltage constant, phase-to-phase	53.6 mV/min
Phase-phase winding resistance	12.4 Ohm
Winding inductance phase-phase	39.8 mH
Winding longitudinal inductivity Ld (phase)	25 mH
Cross inductivity Lq (phase)	29.8 mH
Electric time constant	4.8 ms
Thermal time constant	42 min
Thermal resistance	0.95 K/W
Measuring flange	250 x 250 x 15 mm, steel
Total output inertia moment	0.897 kgcm ²
Product weight	2720 g
Permissible axial shaft load	120 N
Permissible radial shaft load	620 N
Rotor position sensor	Absolute single-turn encoder
Rotor position sensor for manufacturer designation	ECl 1118
Rotor position encoder for absolutely detectable revolutions	1
Rotor position sensor interface	EnDat 22
Rotor position sensor measuring principle	Inductive
Rotor position encoder for DC operating voltage	5 V
Rotor position encoder for DC operating voltage range	3.6 V ... 14 V
Rotor position encoder for positional values per revolution	262144
Rotor position sensor resolution	18 bit
Rotor position encoder system accuracy angle measurement	-120 arcsec ... 120 arcsec
Brake holding torque	4.5 Nm
Brake DC operating voltage	24 V
Brake current consumption	0.5 A
Brake power consumption	12 W
Brake coil resistance	48 Ohm
Brake coil inductivity	1000 mH
Brake separation time	$\leq 55 \text{ ms}$
Brake closing time	$\leq 15 \text{ ms}$
DC brake response delay	$\leq 3 \text{ ms}$
Max. brake no-load speed	10000 rpm
Max. friction work per braking operation	8200 J

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Number of emergency stops per hour	1
Total brake friction work	580 kJ
Brake mass moment of inertia	0.249 kgcm ²
Switching cycles, holding brake	10 million idle actuations (without friction work!)
MTTF, subcomponent	190 years, rotor position encoder