

# Radial gripper DHRC-10-A

Part number: 8125472

FESTO



[PDF](#) General operating condition

## Data sheet

Feature	Value
Size	10
Max. interchangeability	≤0.2 mm
Max. opening angle	180 deg
Rotational symmetry	≤0.2 mm
Pneumatic gripper repetition accuracy	≤0.1 mm
Number of gripper jaws	2
Actuator system	Pneumatic
Mounting position	Any
Mode of operation	Double-acting
Gripper function	Radial
Gripping force backup	Without
Structural design	Connection direction at side Positively driven motion sequence
Position sensing	For proximity sensor
Symbol	00991894
Operating pressure	0.1 MPa ... 0.8 MPa
Operating pressure	1 bar ... 8 bar
Operating pressure	14.5 psi ... 116 psi
Max. operating frequency of pneumatic gripper	≤3 Hz
Min. opening time at 6 bar	28 ms
Min. closing time at 6 bar	43 ms
Operating medium	Compressed air as per ISO 8573-1:2010 [7:4:4]
Information on operating and pilot media	Operation with oil lubrication possible (required for further use)
Corrosion resistance class (CRC)	0 - No corrosion stress
LABS (PWIS) conformity	VDMA24364-B2-L
Suitability for the production of Li-ion batteries	Suitable for battery production with reduced Cu/Zn/Ni values (F1a)
Ambient temperature	-10 °C ... 60 °C
Total gripping torque at 0.6 MPa (6 bar, 87 psi), opening	25.3 Ncm
Total gripping torque at 6 bar, closing	20.4 Ncm
Mass moment of inertia	0.04 kgcm <sup>2</sup>
Maximum force on gripper jaw Fz, static	35 N
Maximum torque on gripper jaw, Mx static	0.5 Nm
Maximum torque on gripper jaw, My static	0.5 Nm
Maximum torque on gripper jaw, Mz static	0.5 Nm
Product weight	54 g

Feature	Value
Type of mounting	Optionally: Direct mounting via through-hole Direct fastening via thread With through-hole and dowel pin With internal thread and dowel pin
Pneumatic connection	M3
Note on materials	RoHS-compliant
Cover cap material	Wrought aluminum alloy, anodized
Housing material	Wrought aluminum alloy, anodized
Gripper jaw material	High-alloy steel